

Unit 7. Channel Estimation and Equalization

ECE-GY 6023. WIRELESS COMMUNICATIONS

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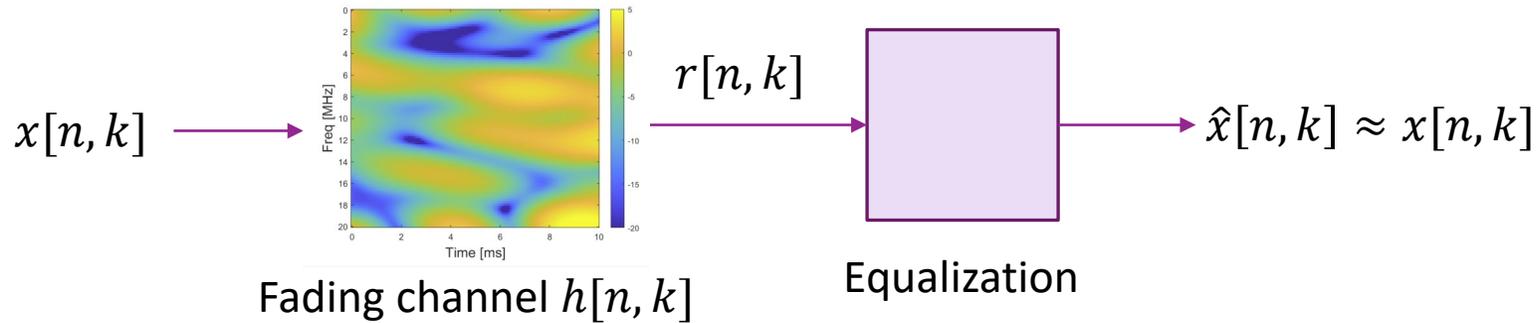
Learning Objectives

- ❑ Describe role of channel estimation in the receiver steps
- ❑ Describe role and configuration of reference signals in OFDM
 - Compute overhead
 - Qualitatively relate density to the coherence time and bandwidth
- ❑ Implement and simulate simple kernel-type channel estimators
- ❑ Compute bias and variance of the kernel estimators
- ❑ Optimize the kernel to minimize the bias + variance error
- ❑ Compute the signal to distortion and noise ratio (SNDR) for a given estimator
- ❑ Measure the SNDR via simulation
- ❑ Implement a simple channel estimator and equalizer for 5G NR downlink

Outline

- ➔ Role of Channel Estimation and Equalization
 - ❑ OFDM Channel Estimation via Kernel Regression
 - ❑ Bias-Variance Tradeoff

Channel Estimation and Equalization



❑ Channels fade in time and frequency

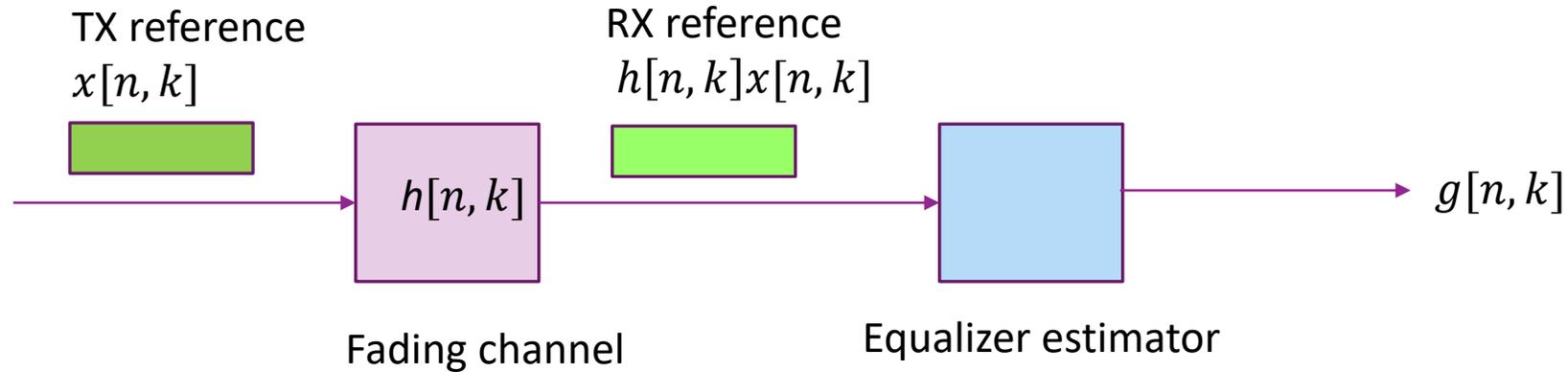
- In OFDM, can be described by time-varying frequency response: $r[n, k] = h[n, k]x[n, k] + w[n, k]$

❑ Equalizers: Estimate TX symbols from faded symbols

- Approximately invert the channel $\hat{x}[k, n] \approx \frac{r[n, k]}{h[n, k]}$ or MMSE $\hat{x}[k, n] = \frac{h[n, k]^* r[n, k]}{|h[n, k]|^2 + N_0}$

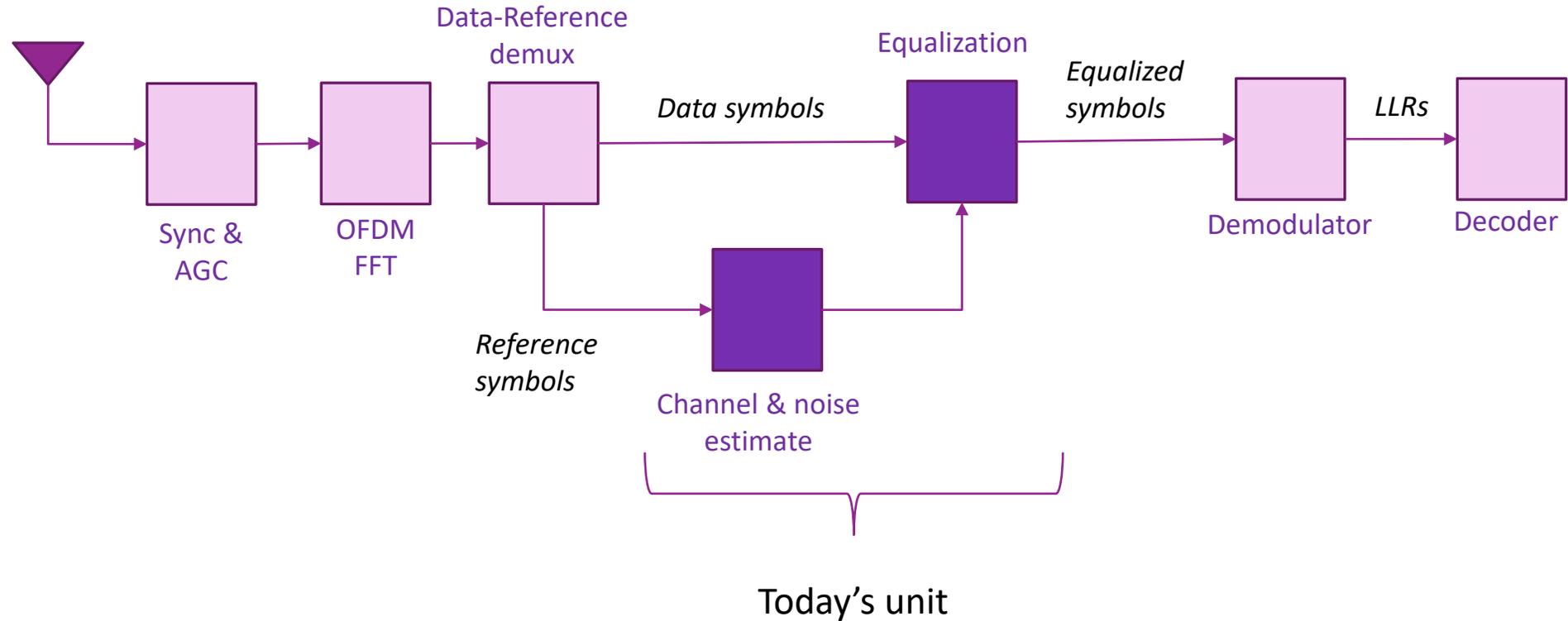
Key challenge: Equalizers need a channel and/or noise estimate

Reference Symbols



- ❑ Equalizers require **training** or **reference** signals
- ❑ TX sends a **known** reference sequence $x[n, k]$ on some locations (k, n)
- ❑ RX sees $r[n, k] = h[n, k]x[n, k] + w[n, k]$
- ❑ Estimates channel $h[n, k]$ and/or equalizer $g[n, k]$ for $r[n, k]$

Receiver Steps in OFDM



Frequency-Domain and Time-Domain EQ

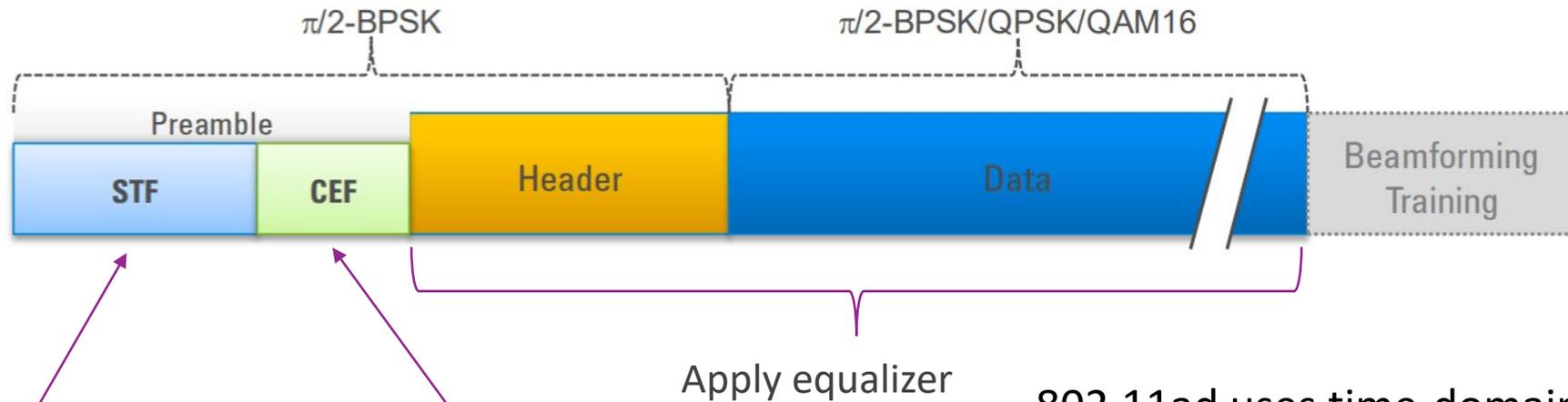
□ Frequency-Domain Equalization:

- Typically, an OFDM channel $r[n, k] = h[n, k]x[n, k] + w[n, k]$
- Estimate frequency-domain channel $h[n, k]$
- Perform equalization with a filter $\hat{x}[n] = g[n, k]r[n, k]$
- Used in 4G, 5G OFDM systems, most 802.11 versions

□ Time-Domain Equalization:

- Model channel in time-domain $r[n] = \sum_k h[k] x[n - k] + w[n]$
- Estimate channel impulse response
- Perform equalization with a filter $\hat{x}[n] = \sum_k g[k] r[n - k]$
- Used in 2G, 3G CDMA systems, 802.11ad single carrier version
- Do not discuss in this unit (except next few slides)

802.11 ad Time-Domain Equalizer



STF: Short training field

- AGC, detection of packet
- coarse estimate of timing
- Process as previous lecture

CEF: Channel estimation field

- Train equalizer

802.11ad uses time-domain equalization

802.11ad Preamble Details



Control packets

Longer STF.

Need to be decoded by all stations. No directional gain

Data packets

Shorter STF

- Based on complementary Golay codes $[Ga, Gb]$
- Have low auto-correlation
- $\frac{1}{T_c} = 1.76 \text{ Gsamp/S}$
- For data packets: STF = $1.23 \mu\text{s}$, CE = $0.654 \mu\text{s}$



Outline

Role of Channel Estimation and Equalization

 OFDM Channel Estimation via Kernel Regression

Bias-Variance Tradeoff

OFDM Channel Estimation

□ OFDM Channel

$$R[n, k] = H[n, k]X[n, k] + W[n, k]$$

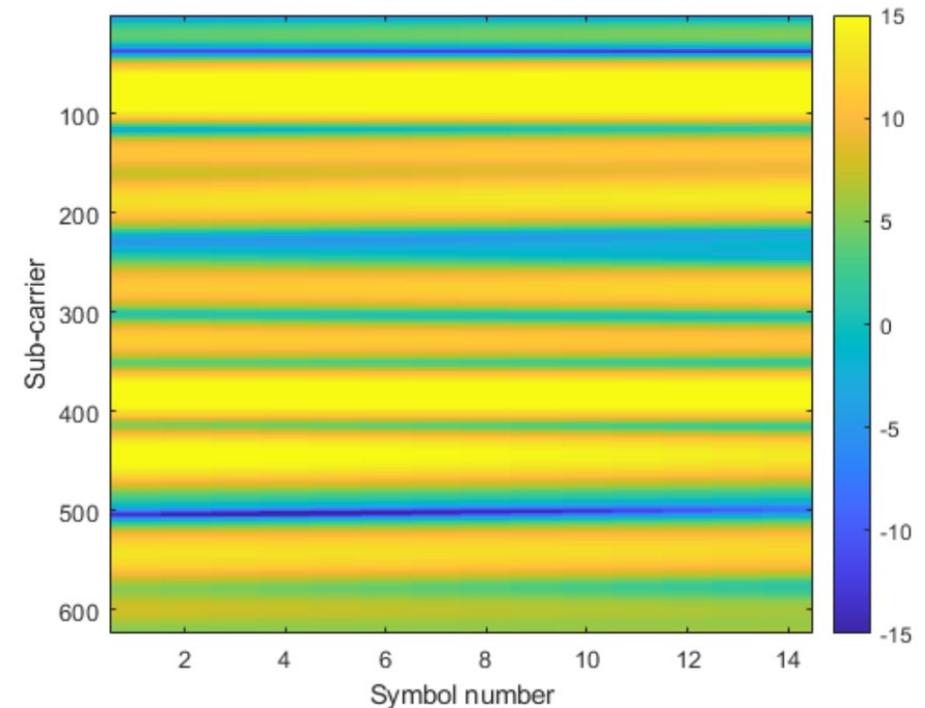
- Symbol k and sub-carrier n

□ Channel $H[n, k]$ varies

- Over time k due to Doppler spread
- Over frequency n due to delay spread

□ Problem: Estimate $H[n, k]$

□ Estimate needed to demodulate data $X[n, k]$



51 RB, 15 kHz SCS, ~10 MHz bandwidth NR slot
500 ns delay spread, 200 Hz Doppler, $\pm 60^\circ$ AoA

Reference Signals

❑ OFDM Channel

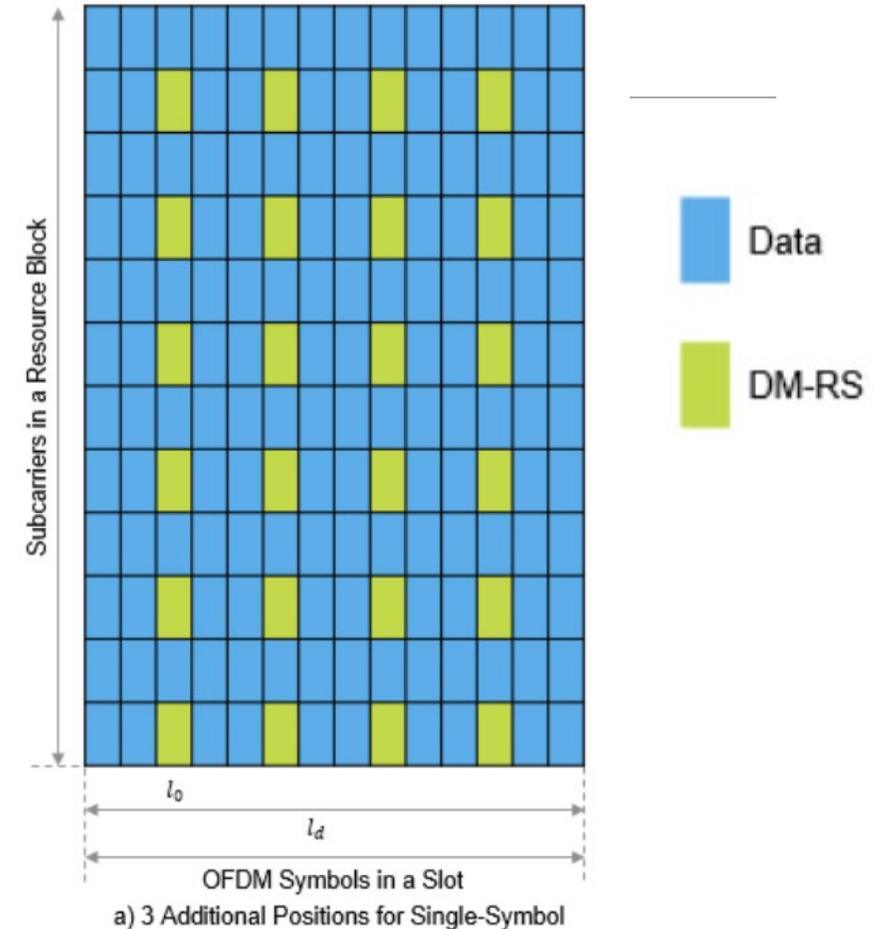
$$R[n, k] = H[n, k]X[n, k] + W[n, k]$$

❑ 5G NR Demodulation Reference Signals

- Called DM-RS
- Transmitted in downlink with data (PDCSH)
- Very configurable in terms of over-head

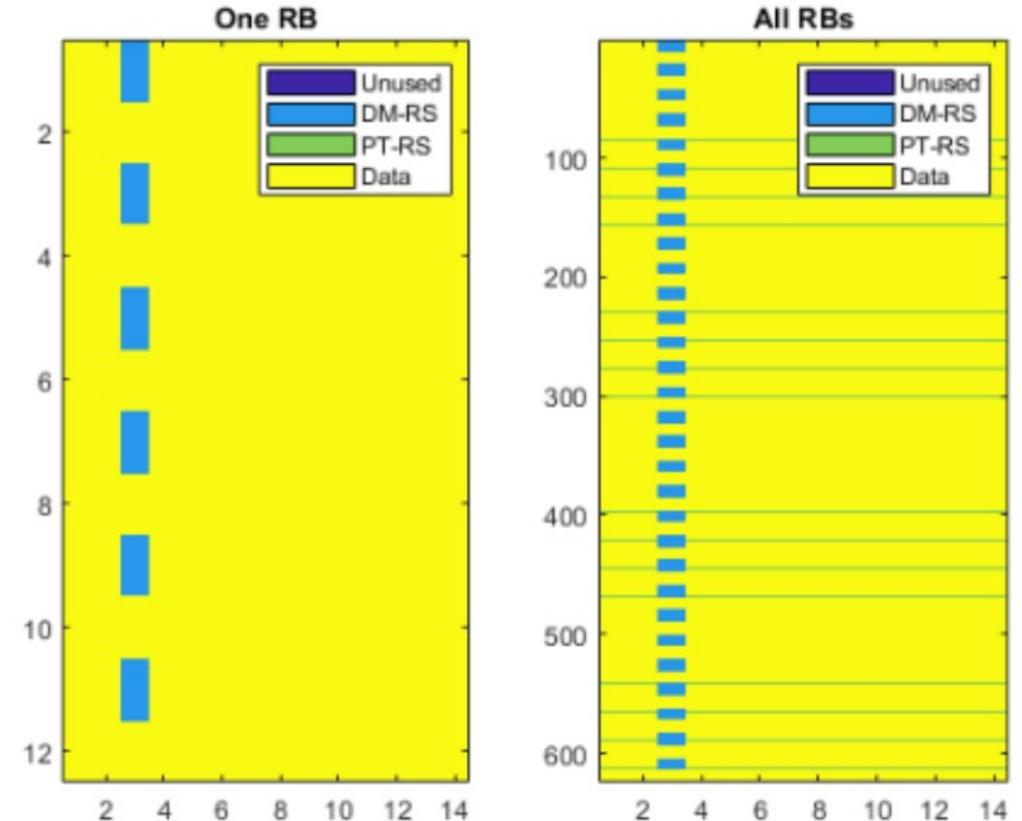
❑ Basic channel estimation idea

- Transmit known $X[n, k]$ on DM-RS.
- Estimate $\hat{H}_0[n, k] \approx R[n, k]/X[n, k]$ on DM-RS symbols
- Interpolate to data symbols



Configuring in DM-RS

- ❑ Example configuration
 - DM-RS on one symbol in RB
 - Occupies 6 out of 12 REs
- ❑ Also added a phase-tracking reference signal
 - Tracks phase variations over time
 - Useful for carrier frequency offset and phase noise (more on this later)
- ❑ Many configurations possible
- ❑ See [excellent MATLAB 5G tutorial](#) with videos



Configuring in MATLAB

❑ MATLAB 5G Toolbox

- Provides all config possibilities
- Easy to use

❑ See [excellent MATLAB 5G tutorial](#) with videos:

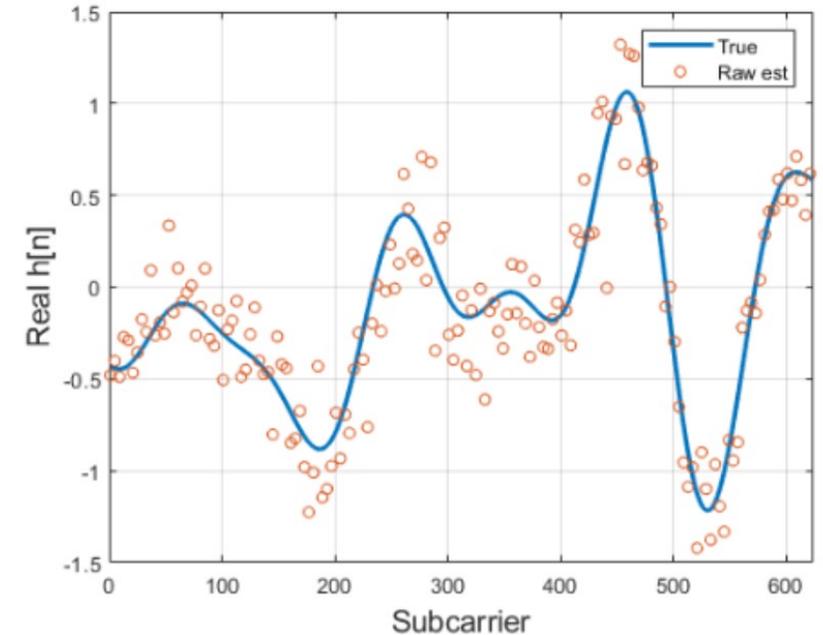
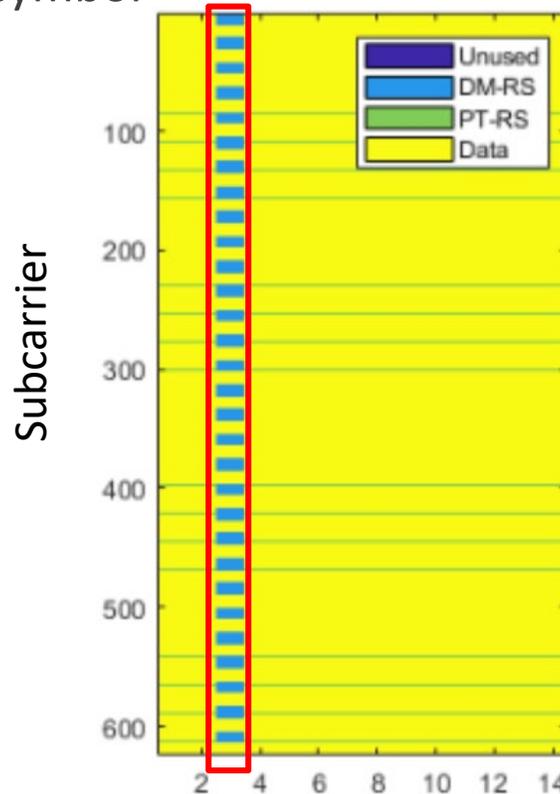
```
% DM-RS config
dmrsConfig = nrPDSCHDMRSConfig(...
    'NumCDMGroupsWithoutData', 1, ... % No unused DM-RS
    'DMRSAdditionalPosition', 0, ... % No additional DM-RS in time
    'DMRSConfigurationType', 1); % 1=6 DM-RS per sym, 2=4 per sym
pdschConfig.DMRS = dmrsConfig;
```

```
% Get the PT-RS symbols and indices
ptrsSym = nrPDSCHPTRS(carrierConfig,pdschConfig);
ptrsInd = nrPDSCHPTRSIndices(carrierConfig,pdschConfig);
```

```
% PDSCH DM-RS precoding and mapping
dmrsSym = nrPDSCHDMRS(carrierConfig,pdschConfig);
dmrsInd = nrPDSCHDMRSIndices(carrierConfig,pdschConfig);
```

Estimating Channel in a Single Symbol

- First consider estimation in one symbol
- True channel is $h[n]$
 - n = sub-carrier index
- RX: $r[n] = h[n]x[n] + w[n]$
- DM-RS $x[n]$ known
- Example to right:
 - 10 MHz bandwidth
 - 200 ns delay spread
 - 10 dB SNR on DM-RS



Raw Channel Estimate

□ Channel: $r[n] = h[n]x[n] + w[n]$

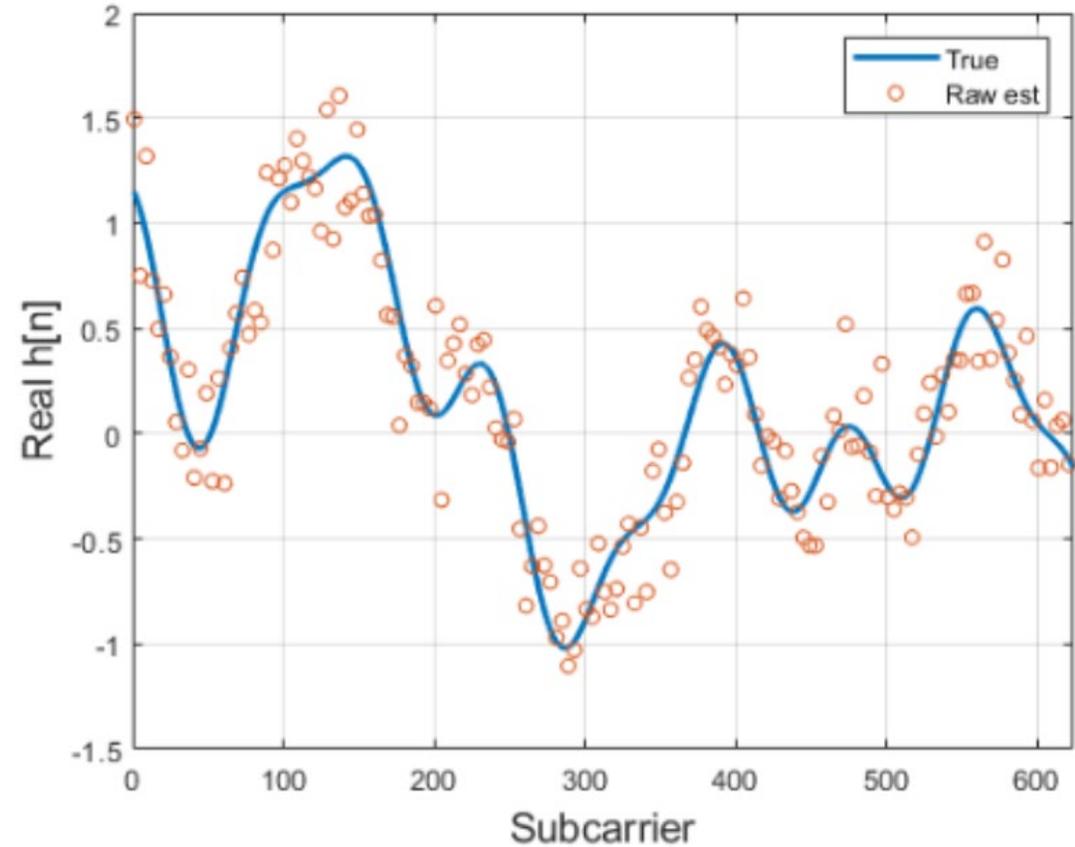
□ On DM-RS positions, $x[n]$ is known

□ Raw channel estimate:

$$\hat{h}_0[n] = \frac{r[n]}{x[n]}$$

- Can be computed in every DM-RS position

□ We see estimate is noisy



Raw Channel Estimate Error

❑ Drop sub-carrier index (since we are looking at one RE)

❑ Channel: $r = hx + w$, $w \sim CN(0, N_0)$, $|x|^2 = E_x$

❑ Raw channel estimate: $\hat{h}_0 = \frac{r}{x} = h + \frac{w}{x}$

❑ Error is

$$E|h - \hat{h}_0|^2 = \frac{1}{|x|^2} E|w|^2 = \frac{N_0}{E_x}$$

❑ Relative error is:

$$\frac{E|h - \hat{h}_0|^2}{|h|^2} = \frac{N_0}{E_x |h|^2} = \frac{1}{\gamma}$$

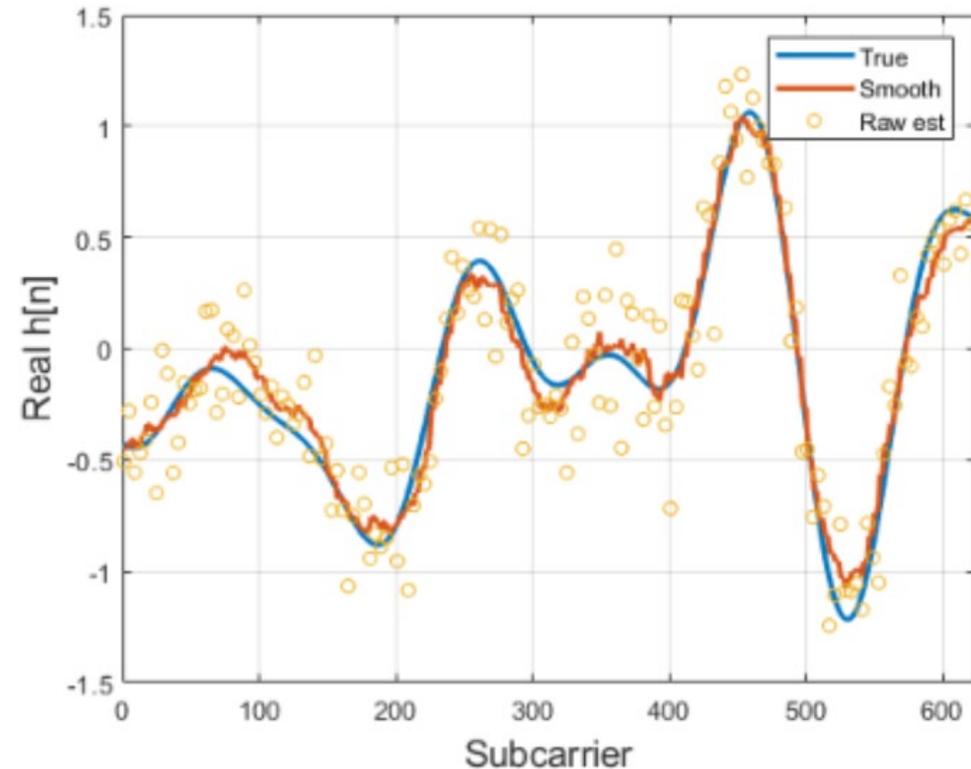
◦ γ = SNR on the symbol

❑ Relative error is the inverse of the SNR



Smoothing the Estimate

- ❑ Raw channel estimates are:
 - Noisy
 - Only available on DM-RS locations
- ❑ Often **smooth** the estimate
 - Fit over all locations
- ❑ Many options
 - Linear interpolation, splines
 - Parametric
- ❑ We look at **Kernel regression**
 - Works well
 - Easy to implement and analyze



Kernel Regression

□ **Problem:** Want to estimate $h[n], n = 1, \dots, N$

- Given noisy values $\hat{h}_0[n] = h[n] + w[n]$
- At locations $n \in I \subset \{0, \dots, N - 1\}$

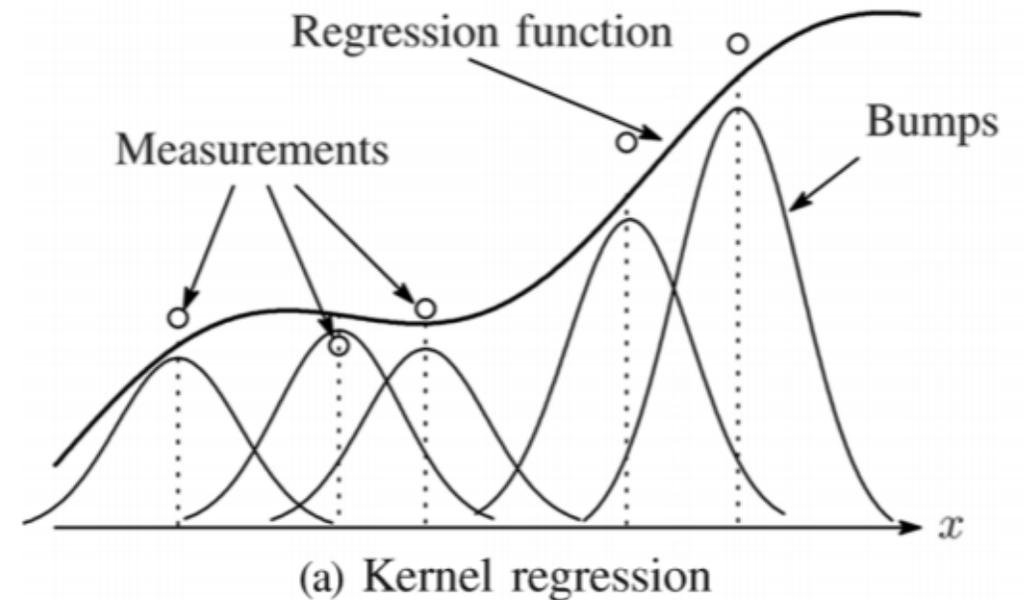
□ **Kernel function** $w[\ell]$

- Example radial basis function: $w[\ell] = e^{-\ell^2/(2\sigma^2)}$
- $\sigma =$ “Bandwidth”

□ **Kernel estimate:** $\hat{h}[n] = \frac{z_1[n]}{z_0[n]}$

- $z_1[n] = \sum_{k \in I} w[n - k] \hat{h}_0[k],$
- $z_0[n] = \sum_{k \in I} w[n - k]$

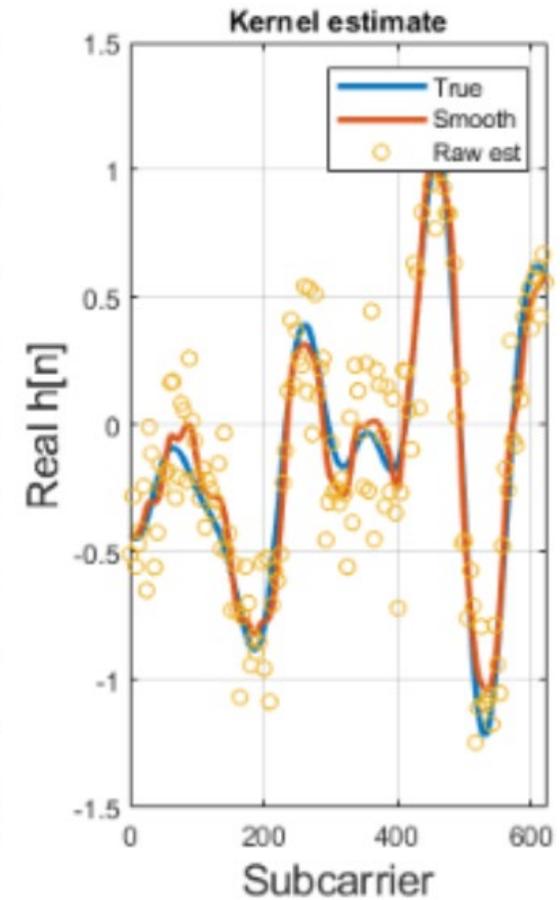
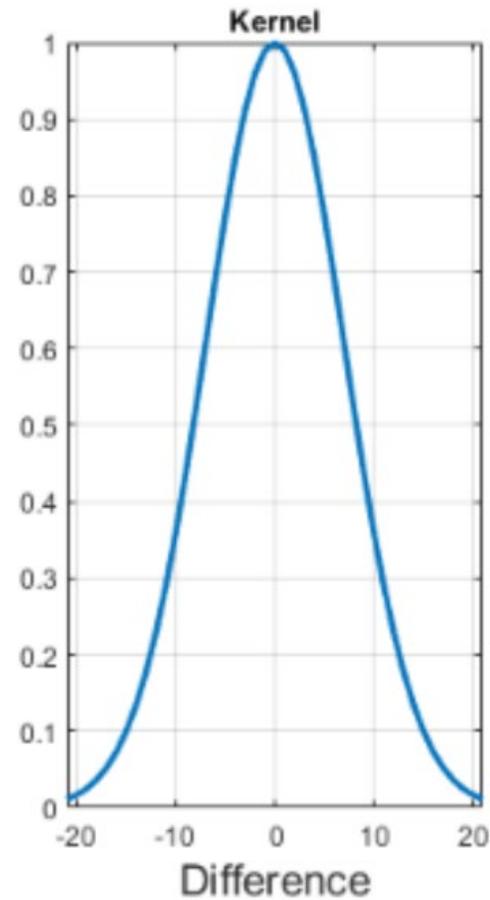
□ **Weights** raw samples by the distance $w[n - k]$



Takeda, Farisu, Milanfar, Kernel Regression for Image Processing and Reconstruction, 2007

Example

- RBF Kernel
 - Bandwidth $\sigma = 7$
 - Length $L = 3\sigma$ on each side
- Estimate is visibly smoother



MATLAB Implementation

- Easy to implement in software or hardware
- See demo

```
% Create random channel
h = randChan(nsc, dlymean, SubcarrierSpacing);

% Add noise
wvar = db2pow(-snr);
rx = h.*tx + sqrt(wvar/2)*(randn(nsc,1) + 1i*randn(nsc,1));

% Get the raw channel estimates on the RS
hestRaw = rx(rsInd)./rsSym;

% Get channel estimate
hest = kernelReg(rsInd, hestRaw, nsc, len, sig);
```

```
function [hest, w] = kernelReg(ind, hestRaw, nsc, len, sig)
% kernelReg: Kernel regression with a RBF

% Create the RBF kernel
w = exp(-0.5*(-len:len).^2/sig^2)';

% Place the raw channel estimates in a vector at the locations
% of the indices.
%   y(ind(i)) = hestRaw(i)
%   y0(ind(i)) = 1
y = zeros(nsc,1);
y0 = zeros(nsc,1);
y(ind) = hestRaw;
y0(ind) = 1;

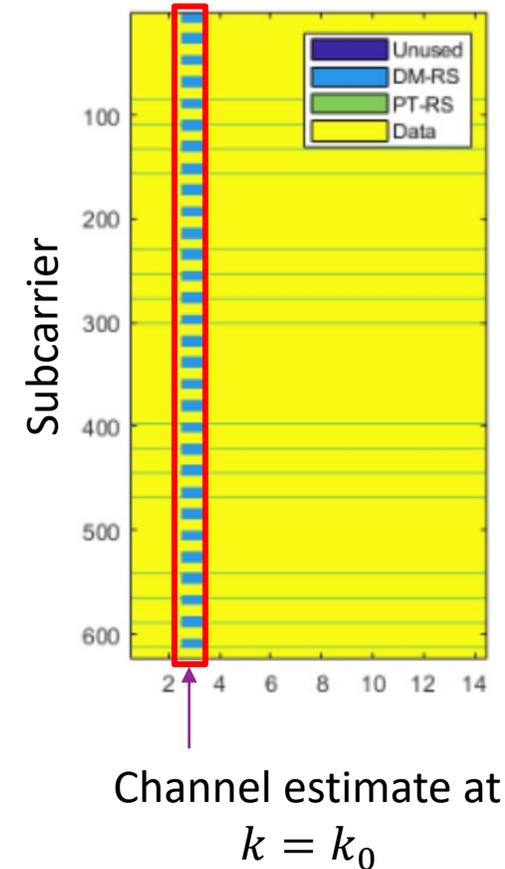
% Get the filter length
len = floor(length(w)/2);

% Filter both raw estimates and the indicators
[z1, z1f] = filter(w,1,y);
z1 = [z1(len+1:end); z1f(1:len)];
[z0, z0f] = filter(w,1,y0);
z0 = [z0(len+1:end); z0f(1:len)];

% Compute the channel estimate
hest = z1./max(1e-8, z0);
end
```

Extending the Estimate to Other Symbols

- Up to now:
 - Estimated at channel at a single OFDM symbol
 - $\hat{H}[n, k_0]$ on OFDM symbol $k = k_0$
- Can be extended to other symbols in slot:
 - $\hat{H}[n, k] = \hat{H}[n, k_0]$
 - Assumes channel is constant over time
 - Coherence time \gg Slot time
- Can also have multiple RS symbols
 - Useful when there is time variations in slot
- See lab



In-Class Exercise

In-Class Exercise

For each channel, find the fraction of the REs used by the channel.

Roughly, estimate the number of DM-RS symbols per coherence BW

Outline

- Role of Channel Estimation and Equalization
- OFDM Channel Estimation via Kernel Regression
-  □ Bias-Variance Tradeoff

Mean Squared Error with Kernel Regression

- Problem: True channel $h[n], n = 1, \dots, N$
 - Given noisy values $\hat{h}_0[n] = h[n] + v[n]$ at sub-carriers $n \in I$.

- Kernel estimate: $\hat{h}[n] = \frac{z_1[n]}{z_0[n]}$
 - $z_1[n] = \sum_{k \in I} w[n-k] \hat{h}_0[k], z_0[n] = \sum_{k \in I} w[n-k]$

- Mean-squared error:

$$MSE[n] = E|\hat{h}[n] - h[n]|^2$$

- Measures the accuracy of the estimate
- For now, model $h[n]$ as deterministic
- Average over noise $v[n]$

- May also be interested in the **normalized MSE**: $NMSE[n] = \frac{E|\hat{h}[n] - h[n]|^2}{|h[n]|^2}$

Bias and Variance Error

- ❑ Error: $e[n] = h[n] - \hat{h}[n]$
- ❑ Since $\hat{h}[n]$ is linear in \hat{h}_0 can write $e[n] = e_s[n] - e_v[n]$
 - Signal component: $e_s[n] = h[n] - \frac{1}{z_0[n]} \sum_{k \in I} w[n-k]h[k]$
 - Noise component: $e_v[n] = \frac{1}{z_0[n]} \sum_{k \in I} w[n-k]v[k]$
- ❑ MSE can be written as two components:

$$MSE[n] = Bias^2[n] + Var[n]$$

- Bias error: $Bias^2[n] = |e_s[n]|^2$
- Variance error: $Var[n] = E|e_v[n]|^2$

Variance Error

□ Noise term $e_v[n] = \frac{1}{z_0[n]} \sum_{k \in I} w[n-k]v[k]$

□ Recall $E|v[n]|^2 = \frac{N_0}{E_x}$,

- N_0 = noise on the reference signals, E_x = Reference signal energy

□ Variance on the kernel estimate is:

$$\text{Var}[n] = E|e_v[n]|^2 = \frac{\sum_{k \in I} |w[n-k]|^2 N_0}{|\sum_{k \in I} w[n-k]|^2 E_x}$$

□ Proof:

- Since $v[n]$ are uncorrelated, $E|e_v[n]|^2 = \frac{\sum_{k \in I} |w[n-k]|^2 E|v[k]|^2}{|z_0[n]|^2}$
- Substitute expressions for $z_0[n] = \sum_{k \in I} w[n-k]$ and $E|v[k]|^2 = \frac{N_0}{E_x}$

Variance Error for a Uniform Kernel

□ Example: Uniform kernel

$$w[\ell] = \begin{cases} 1 & \text{if } |\ell| \leq L \\ 0 & \text{else} \end{cases}$$

- Length $2L + 1$

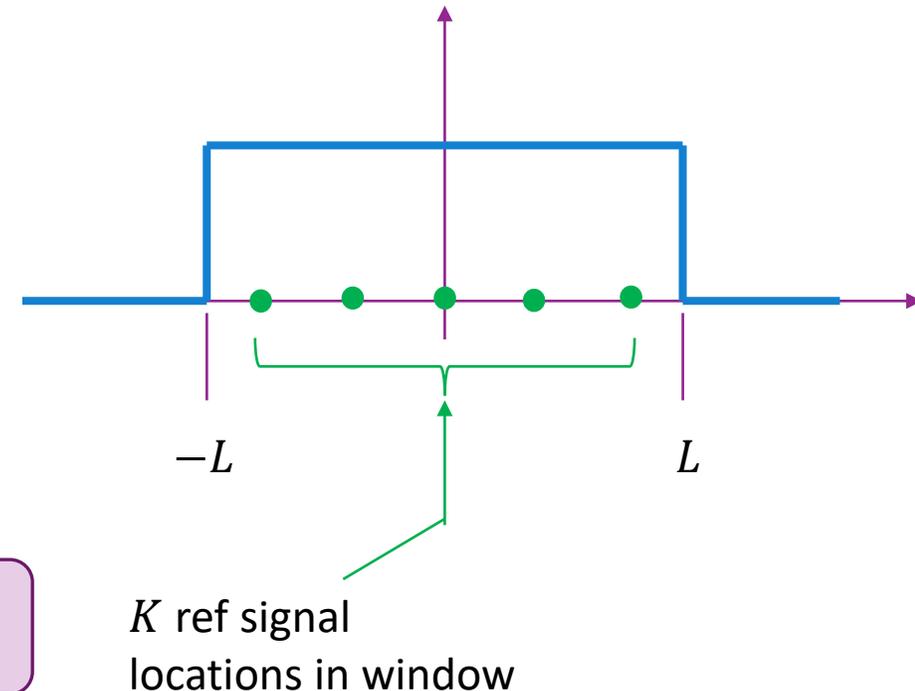
□ Suppose that there are K reference signals in window

□ Variance error: $Var[n] = \frac{N_0}{KE_x}$

- Why? $Var[n] = E|e_v[n]|^2 = \frac{\sum_{k \in I} |w[n-k]|^2 N_0}{|\sum_{k \in I} w[n-k]|^2 E_x} = \frac{K N_0}{K^2 E_x}$

□ Conclusion: Variance error decreases with kernel width

In general, increasing kernel width, decreases variance error



Bias Error

□ Signal error:

- $e_s[n] = h[n] - \frac{1}{z_0[n]} \sum_{k \in I} w[n-k] h[k] = h[n] - \bar{h}[n]$

□ $\bar{h}[n]$ = local average of $h[k]$

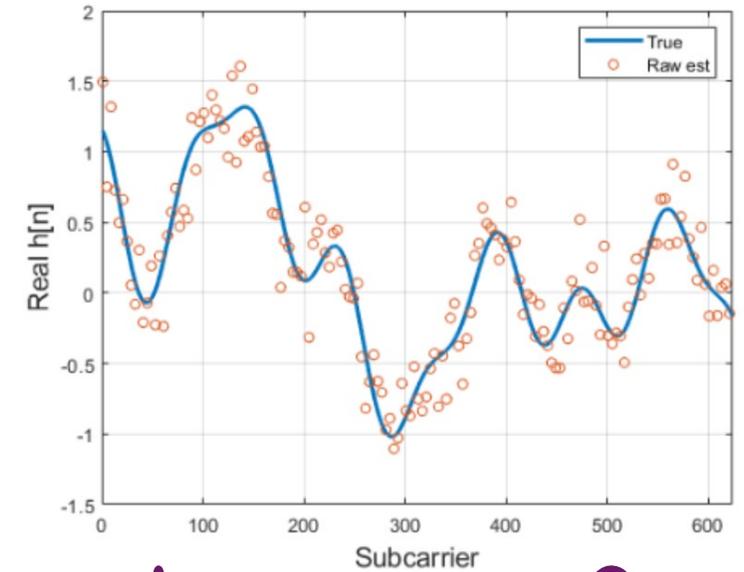
- Write as: $\bar{h}[n] = \sum_{k \in I} \alpha_{n-k} h[k]$, $\alpha_{n-k} = \frac{w[n-k]}{\sum_{k \in I} w[n-k]}$

- Weighted average of values of $h[k]$
- Weights α_ℓ sum to one

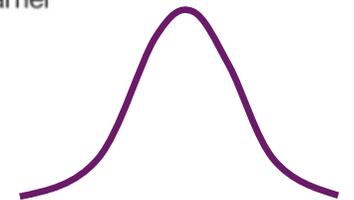
□ Bias error, $|e_s[n]|^2$, is large when:

- Average over region where $h[n]$ changes significantly
- Window \geq Coherence bandwidth / time

In general, increasing kernel increases the bias error



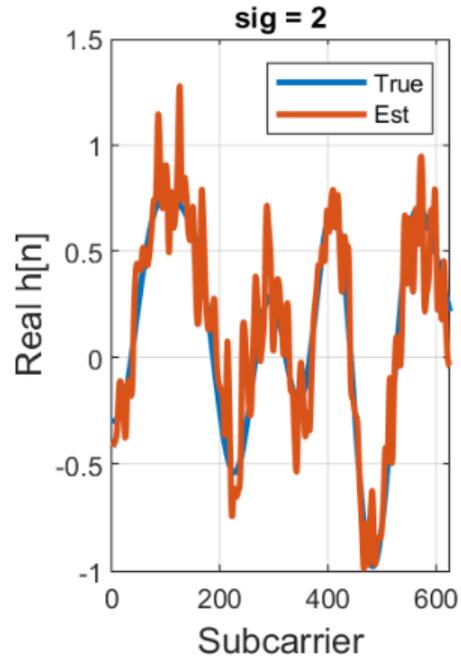
Low bias error
Kernel width
 \ll Coherence BW



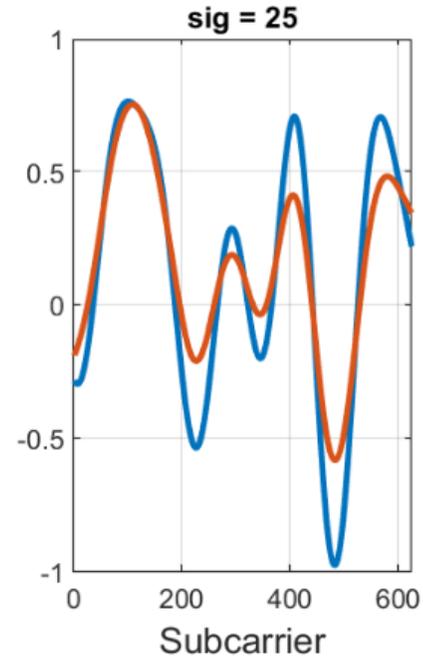
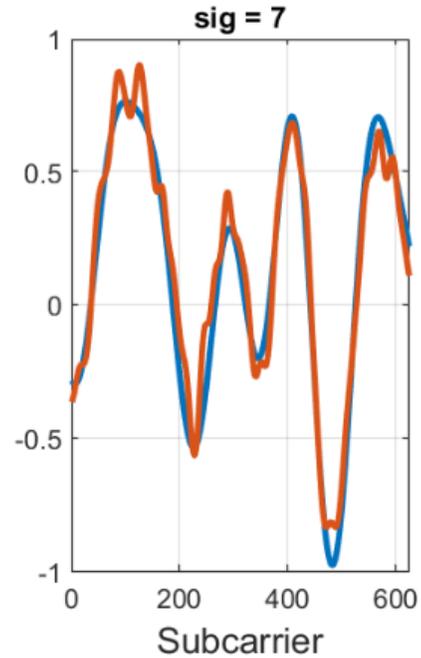
High bias error
Kernel width
 \geq Coherence BW

Bias-Variance Tradeoff

Decreasing
kernel width



High variance
Too low averaging



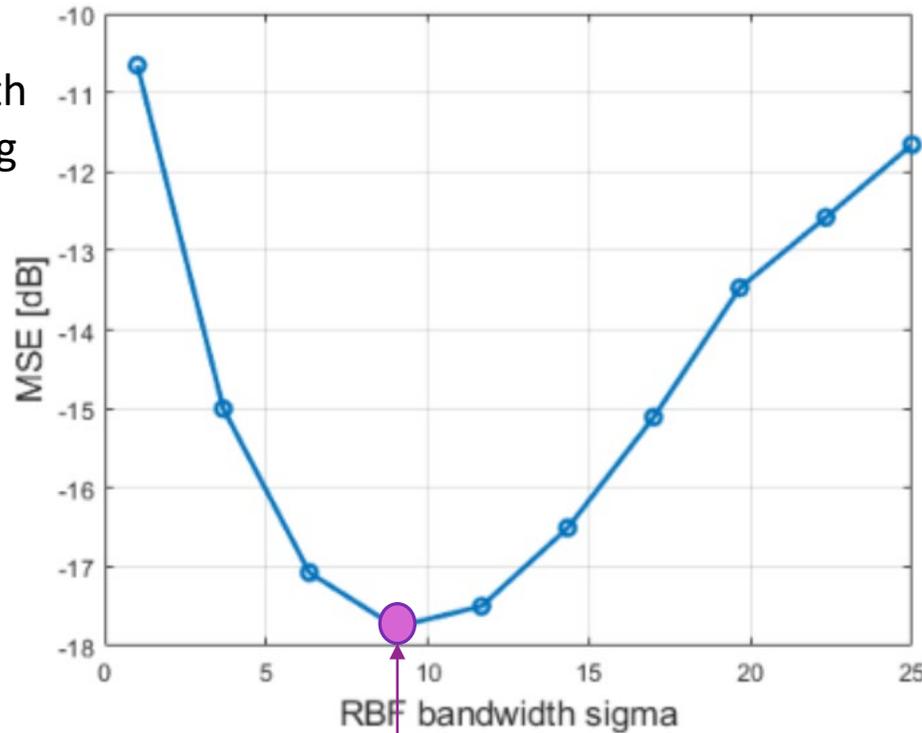
High bias
Too much averaging

Increasing
kernel width



Bias-Variance Tradeoff

High variance
Small kernel width
Too low averaging



Optimal

High bias

High kernel width
Too much averaging



□ This example:

- Mean delay spread, $\delta = 200$ ns
- Coherence BW, $W_{coh} = \frac{1}{2\delta} = 2.5$ MHz
- Optimal width:
 $\sigma = 9$ subcarriers
 $\sigma = 135$ kHz
- We see: $\sigma \ll W_{coh}$



Modeling Channel Estimation Error

- ❑ Channel estimation error: $\hat{h} = h + v$
- ❑ Channel estimation error has two components: $E|v|^2 = Bias^2 + Var$
 - Each term depends on level of averaging in the kernel estimator
- ❑ Bias error:
 - Typically scales with the channel power
 - Since medium is linear, increasing TX power will not change the relative kernel error
 - Assume $Bias^2 = c_b|h|^2$
 - Constant c_b increases with the kernel width
- ❑ Variance error:
 - From earlier, we can write $Var = c_v \frac{N_0}{E_x}$, $c_v = \frac{\sum_{k \in I} |w[n-k]|^2}{|\sum_{k \in I} w[n-k]|^2}$
 - Constant c_v decreases with the kernel width



Effective Noise in Equalization

□ Consider channel on a single resource element:

- Channel: $r = hx + w$, $w \sim CN(0, N_0)$, $E|x|^2 = E_x$
- SNR is $\gamma_0 = \frac{E_x |h|^2}{N_0}$

□ Simple model for channel estimation error: $\hat{h} = h + v$, $v \sim CN(0, N_v)$

- Bias+ variance channel estimation error: $N_v = c_b |h|^2 + \frac{c_v N_0}{E_x}$

□ Consider equalized estimate:

$$z = \hat{h}^* r = (h + v)^* (hx + w) = |h|^2 x + n,$$

- Total $n = (h + v)^* w + v^* hx$
- Neglecting cross terms: $n \approx h^* w + v^* hx$

□ Total **effective noise**, n , has two terms:

- Original noise: $h^* w$
- Distortion from channel estimation error: $v^* hx$

Signal-to-Noise and Distortion (SNDR)

- Equalized symbol:

$$z = \hat{h}^* r = (h + v)^*(hx + w) = |h|^2 x + n, \quad n \approx h^* w + v^* hx$$

- Signal energy: $E_s = |h|^4 E_x$

- Total effective noise energy:

- Error energy is $N_{tot} = E|n|^2 = |h|^2 N_0 + N_v |h|^2 E_x$

- Signal-to noise and distortion (SNDR):

$$\gamma = \frac{\gamma_0}{1 + c_v + c_b \gamma_0}$$

- Proof: $\gamma = \frac{E_s}{N_{tot}} = \frac{|h|^4 E_x}{|h|^2 N_0 + |h|^2 E_x N_v} = \frac{|h|^2 E_x}{N_0 + N_v E_x}$
- Substitute in $N_v = \frac{c_v N_0}{E_x} + c_b |h|^2$



SNDR Regimes

□ SNDR: $\gamma = \frac{\gamma_0}{1+c_v+c_b\gamma_0}$

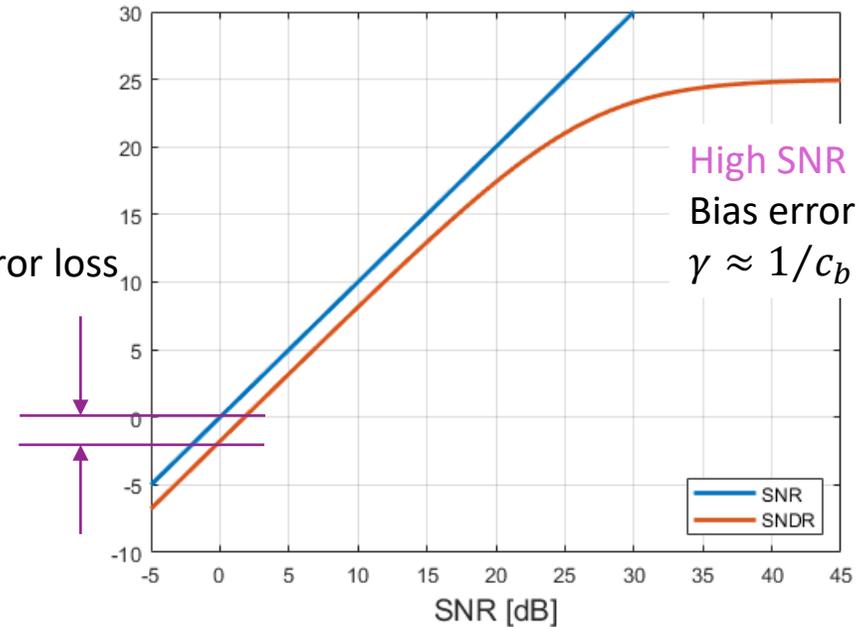
□ Low SNR regime:

- $\gamma \approx \frac{\gamma_0}{1+c_v}$
- Loss in SNR of $\frac{1}{1+c_v}$
- Limited by variance error, c_v

□ High SNR regime:

- $\gamma_0 \approx \frac{1}{c_b}$
- Limited by bias error, c_b

Low SNR
Variance error loss
 $1/(1+c_v)$



Estimating Effective Noise

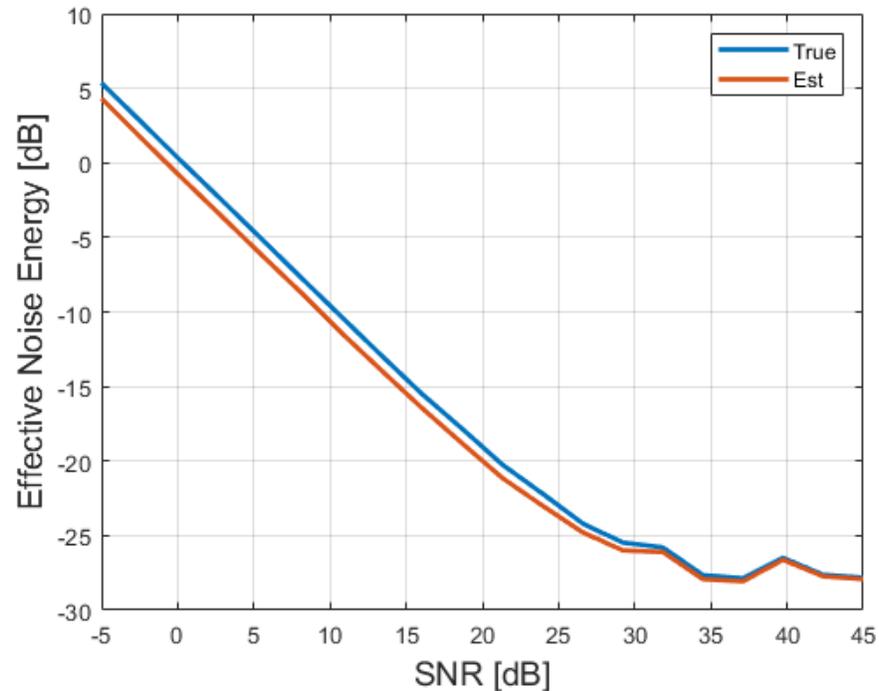
- ❑ For equalization and LLR calculations we need to estimate the effective noise
- ❑ Noise estimation can be performed via **residual error**:
 - Reference symbols: $r_n = h_n x_n + w_n$, $n = 1, \dots, N_{RS}$
 - Obtain channel estimate: \hat{h}_n (e.g., via kernel regression)
 - **Effective noise estimate**: $\hat{N}_{RS} = \frac{1}{N_{RS}} \sum_n |r_n - \hat{h}_n x_n|^2$
- ❑ Residual error estimate captures noise and distortion
 - If $\hat{h}_n = h_n + v_n$, then $r_n - \hat{h}_n x_n = r_n - h_n x_n + v_n x_n = w_n + v_n x_n$
- ❑ But the residual error estimate is biased:
 - Under-estimates the variance error in the distortion
 - Measuring error on the symbols used in training
 - Can compensate by scaling the noise estimate before using in the equalizer or demodulator



Measuring True Effective Noise

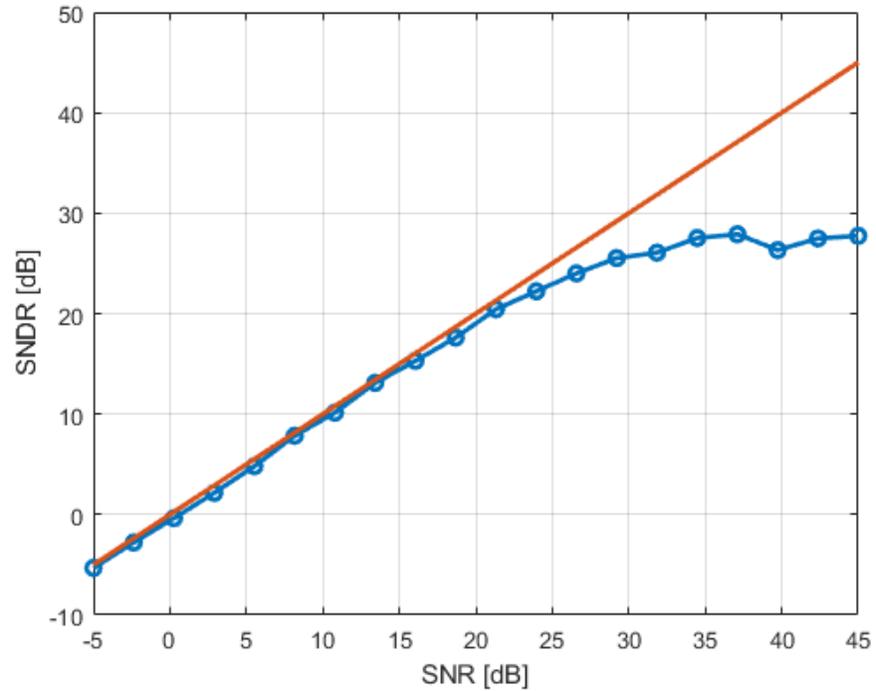
- ❑ From previous slide, residual error noise estimate is biased
 - Under-estimates the variance error
 - Uses training symbols for error estimation
- ❑ To more accurately measure noise, use separate set of **test symbols**
 - Get test symbols: $r_n = h_n x_n + w_n$, $n = 1, \dots, N_{test}$
 - These symbols are distinct from the RS used in training
 - Error estimate on the test: $\hat{N}_{test} = \frac{1}{N_{test}} \sum_n |r_n - \hat{h}_n x_n|^2$
- ❑ Rarely used during actual operation of the receiver
 - Adding test symbols adds excessive overhead
- ❑ But, the test symbols can be done in test and simulation
 - For example, populate data symbols with known symbols

Noise Estimation Simulation



- ❑ Simulation parameters as before
 - Mean delay spread, $\delta = 200$ ns
 - Coherence bandwidth, $W_{coh} \approx \frac{1}{2\delta} = 2.5$ MHz
 - One RS per 4 sub-carriers: 60 kHz
- ❑ “True” noise measured on data symbols
 - Not used in training
- ❑ “Estimated” noise measured on RS symbols
- ❑ We see:
 - Estimated noise is slightly optimistic at low SNRs
 - Both true and estimated noise levels off at high SNR
 - Limited by bias SNR

SNDR in Practice



- Estimated the SNDR from effective noise estimate
- In this simulation:
 - About 0.4 dB loss at low SNRs
 - About 27 dB saturation

In-Class Exercise

In-Class Exercise: Degradation in BER due to Channel Estimation

Modify the above program to:

- Populate the reference symbols with QPSK as before
- Populate the data symbols with 16-QAM
- Measure the BER on the data symbols as a function of the SNR for both perfect channel estimation and actual channel estimation.
- Plot the two BER values

