

Multiple Antennas and Beamforming

EL-GY 6023. WIRELESS COMMUNICATIONS

PROF. SUNDEEP RANGAN

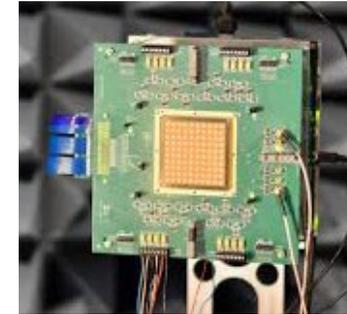


Outline

- ➔ Antenna arrays and the Spatial Signature
 - Receive Beamforming and SNR Gain
 - Array Factor
 - Multiple paths and Diversity
 - Transmit Beamforming

Antenna Arrays

- ❑ **Antenna arrays:** Structure with multiple antennas
 - At TX and/or RX
 - Key to 5G mmWave and massive MIMO
- ❑ Two key benefits
- ❑ **Beamforming:** This lecture
 - Concentrate power in particular directions
 - Increases SNR and may enable spatial diversity
 - Requires arrays at *either* TX or RX
- ❑ **Spatial multiplexing:** Next lecture
 - Enables transmission in multiple virtual paths
 - Increases degrees of freedom
 - Requires multiple antennas at *both* TX and RX



IBM 28 GHz array
32 element dual
polarized array
Sadhu et al, ISSCC 2017



Aurora C-Band Massive
MIMO array
64 elements, 5-6 GHz
<https://www.taoglas.com/>

Multiple Receive Antennas

- ❑ Single Input Multiple Output

- One TX antenna
- M RX antennas

- ❑ Transmit a scalar signal $x(t)$

- ❑ Receive a vector of signals:

- $\mathbf{r}(t) = (r_1(t), \dots, r_M(t))^T$

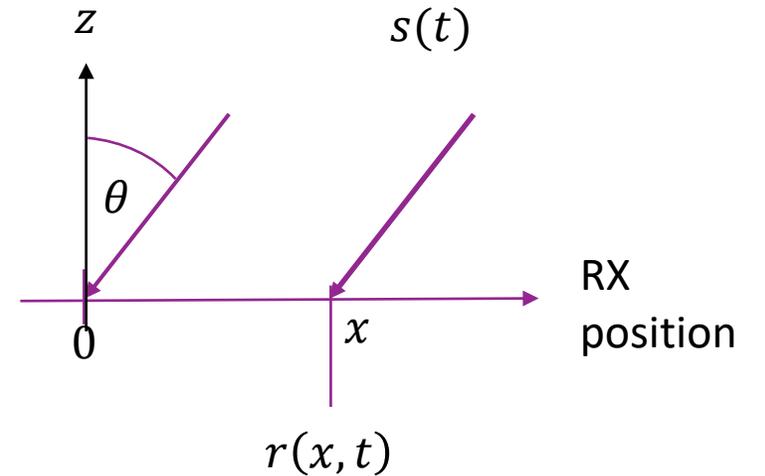
- ❑ What is the channel from $x(t)$ to $\mathbf{r}(t)$?

- ❑ Want channel in complex baseband



Channel vs. Position

- ❑ To understand SIMO channel, consider **single path channel**
 - AoA of θ relative to z-axis
 - Delay τ_0 to origin
 - Gain A is constant close to origin
- ❑ Transmit signal $s(t)$ and look at response at position x
- ❑ Consider a RX position close to origin
 - $B|x| \ll f_c \lambda$, B = bandwidth of $s(t)$
- ❑ **Phase rotation with displacement:**
 - Baseband response at x is (proof on next slide):



$$r(x, t) \approx \underbrace{e^{2\pi j x \sin \theta / \lambda}}_{\text{Phase rotation with } x} \underbrace{r(0, t)}_{\text{Response at } x = 0}$$

Proof of Phase Rotation with Displacement

□ Delay of path at x is: $\tau(x) = \tau_0 - \frac{x \sin \theta}{c}$

□ Baseband response at x :

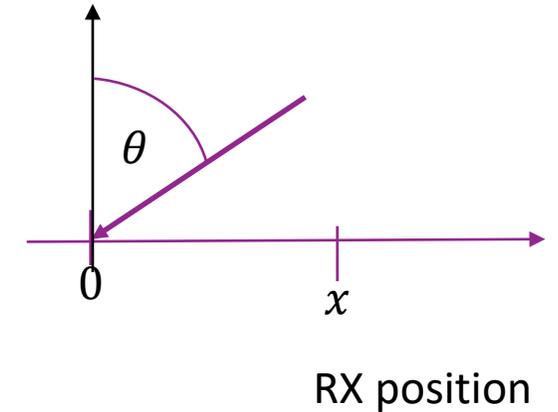
$$r(x, t) = Ae^{-j\omega_c \tau_0} e^{2\pi j x \sin \theta / \lambda} s(t - \tau(x))$$

□ Also, $s(t - \tau(x)) \approx s(t - \tau_0)$ if $B|\tau(x) - \tau_0| \ll 1$

□ But, by assumption of small displacement:

$$B|\tau(x) - \tau_0| \leq \frac{B|x|}{c} = \frac{B|x|}{\lambda f_c} \ll 1$$

□ Hence, $r(x, t) \approx Ae^{-j\omega_c \tau_0} e^{2\pi j x \sin \theta / \lambda} s(t - \tau_0) = e^{2\pi j x \sin \theta / \lambda} r(0, t)$



RX position

Response for a ULA

Uniform Linear array (ULA)

- M antenna positions spaced d apart

Transmit signal $s(t)$

- Channel single path with AoA θ , gain A

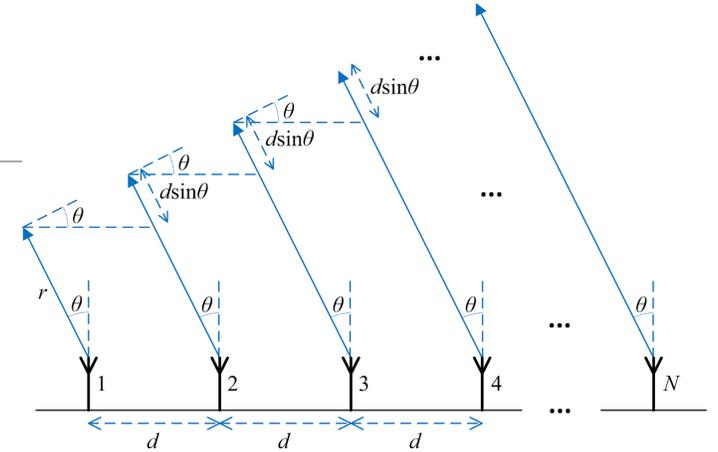
Response at position: $r_m(t) = Ae^{-j\omega\tau_0} e^{2\pi j(n-1)d \sin \theta/\lambda} s(t - \tau_0)$

SIMO frequency response is:

$$\mathbf{h}(\theta, \omega) = Ae^{-j\omega\tau_0} \begin{bmatrix} e^{2\pi j 0 d \sin \theta/\lambda} \\ \vdots \\ e^{2\pi j (M-1) d \sin \theta/\lambda} \end{bmatrix} = g(\omega) \mathbf{u}(\theta)$$

Scalar response at $x = 0$

Phase shifts across elements



Response Decomposition

□ For a single path channel, the frequency response has two components:

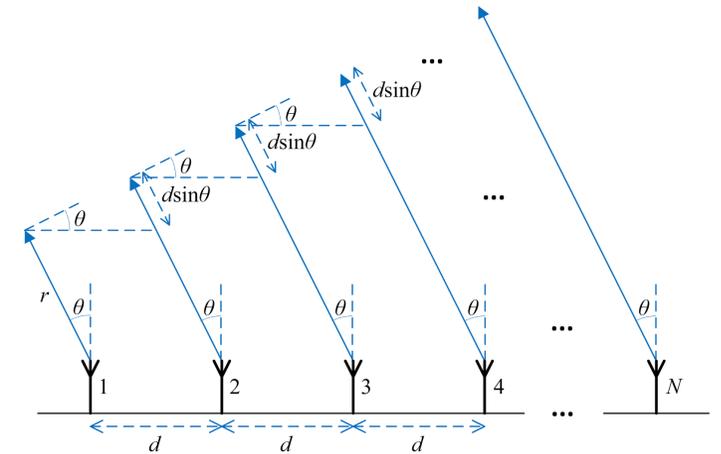
$$\mathbf{h}(\theta, \omega) = g(\omega)\mathbf{u}(\theta)$$

□ Scalar channel response, $g(\omega)$

- $g(\omega) = Ae^{-j\omega\tau_0}$
- Response at a reference position in array

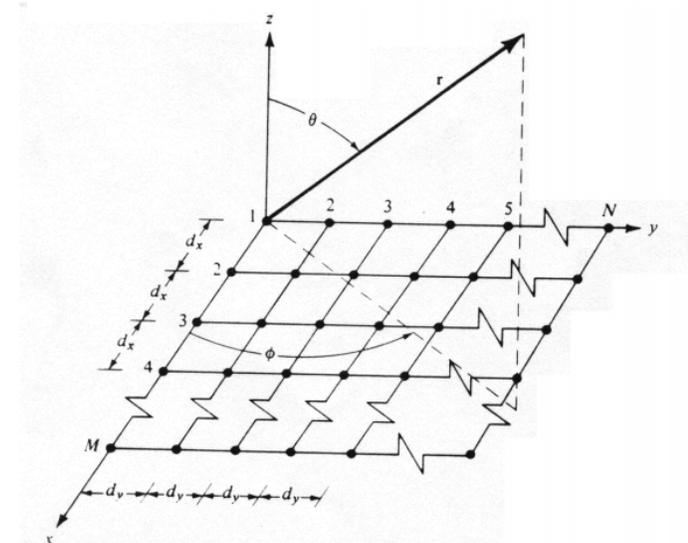
□ Vector spatial signature, $\mathbf{u}(\theta)$

- $\mathbf{u}(\theta) = \begin{bmatrix} e^{2\pi j 0 d \sin \theta / \lambda} \\ \vdots \\ e^{2\pi j (M-1) d \sin \theta / \lambda} \end{bmatrix}$
- Vector of phase shifts from the reference
- Also called the **steering vector** (reason for name will be clear later)



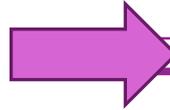
Array Response in 3D

- Many arrays place elements over 2D area
- Uniform rectangular array (URA):
 - $M \times N$ grid of elements
 - Spaced d_x and d_y
 - Also called uniform planar array (UPA)
- Incident angle $\Omega = (\phi, \theta)$
 - (Azimuth, elevation) or (azimuth, inclination)
- Spatial signature:
 - $u_{mn}(\Omega)$ = complex response to antenna (m, n)
 - $u_{mn}(\Omega) = \exp \left[\frac{2\pi i}{\lambda} (m d_x \sin \theta \cos \phi + n d_y \sin \theta \sin \phi) \right]$



Outline

Antenna arrays and the Spatial Signature

 Receive Beamforming and SNR Gain

Array Factor

Multiple paths and Diversity

Transmit Beamforming

Multiple Receive Antennas

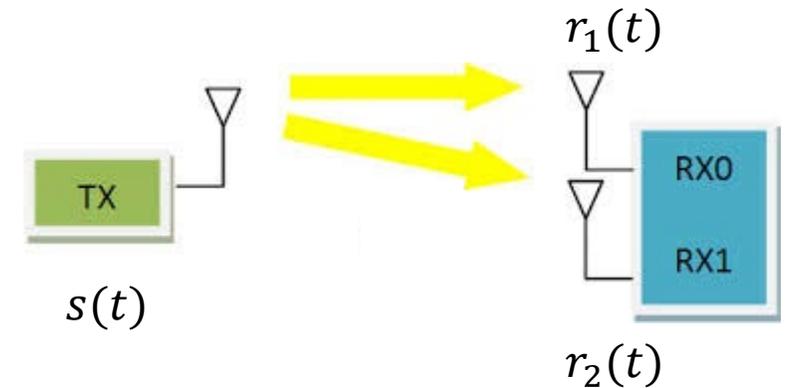
- Single Input Multiple Output

- One TX antenna
- M RX antennas

- Transmit a scalar signal $s(t)$

- Receive a vector of signals:

- $\mathbf{r}(t) = (r_1(t), \dots, r_M(t))^T$



- **Basic question:** How do we decode signal $x(t)$ from vector $\mathbf{r}(t)$?

Scalar Multiple Channel Problem

□ Consider transmission of a single symbol x

□ Receive a vector across M channels:

$$\mathbf{r} = \mathbf{h}x + \mathbf{n} = \begin{pmatrix} h_1 \\ \vdots \\ h_M \end{pmatrix} x + \begin{pmatrix} n_1 \\ \vdots \\ n_M \end{pmatrix}$$

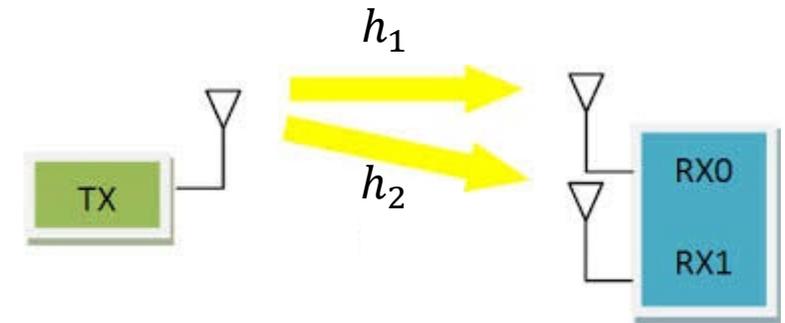
- x : Scalar TX symbol
- \mathbf{h} : Vector of channel weights, \mathbf{n} : Vector of noise

□ Channel can be from many different paths:

- multiple times, frequencies or antennas

□ Applies to a single degree of freedom (time or frequency)

□ **Question:** How do we detect scalar x from vector \mathbf{r} ?



Linear Combining

❑ RX model: $\mathbf{r} = \mathbf{h}x + \mathbf{n}$

- 1 input, M outputs

❑ Linear combining: Take a linear combination

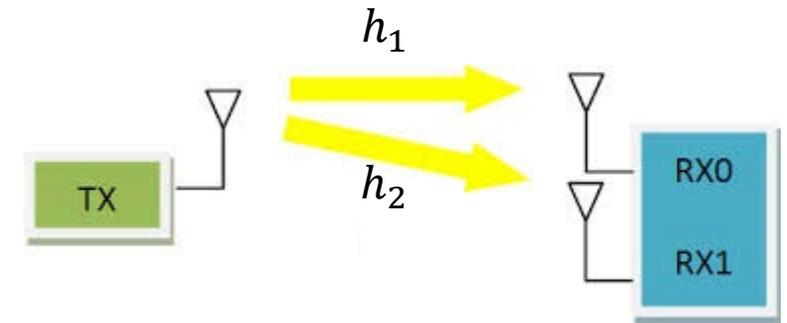
$$\begin{aligned} z &= \mathbf{w}^* \mathbf{r} = (\mathbf{w}^* \mathbf{h})x + \mathbf{w}^* \mathbf{n} \\ &= \alpha x + v \end{aligned}$$

❑ \mathbf{w} is called the **weighting vector**

- Called the **beamforming vector** for multiple antennas

❑ Creates **effective SISO** channel:

- 1 input x , 1 output symbol z
- Gain: $\alpha = \mathbf{w}^* \mathbf{h}$
- Noise: $v = \mathbf{w}^* \mathbf{n}$



Linear Combining Analysis

Linear combining: $z = \mathbf{w}^* \mathbf{r} = (\mathbf{w}^* \mathbf{h})x + \mathbf{w}^* \mathbf{n}$

- Gain: $\alpha = \mathbf{w}^* \mathbf{h}$
- Noise: $v = \mathbf{w}^* \mathbf{n}$

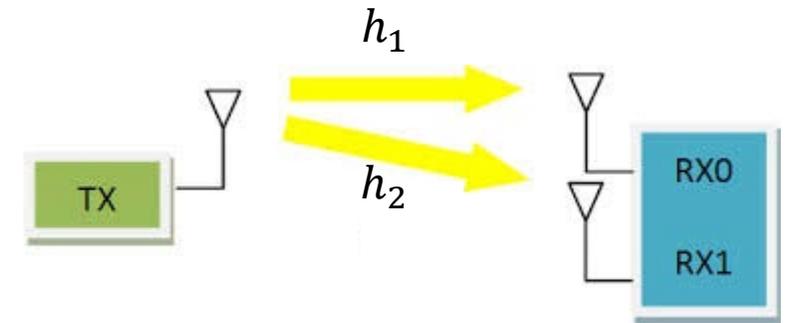
Analysis: Let

- $E_x = E|x|^2 =$ average symbol energy
- Assume noise $n_m \sim CN(0, N_0)$ (i.i.d. complex Gaussian noise)

Then, after combining;

- Signal energy = $|\mathbf{w}^* \mathbf{h}|^2 E_x$
- Noise: v is Gaussian with $E|v|^2 = \|\mathbf{w}\|^2 N_0$
- SNR is:

$$\gamma = \frac{|\mathbf{w}^* \mathbf{h}|^2 E_x}{\|\mathbf{w}\|^2 N_0}$$



Maximum Ratio Combining

From previous slide: SNR is $\gamma = \frac{|\mathbf{w}^* \mathbf{h}|^2 E_x}{\|\mathbf{w}\|^2 N_0}$

Maximum ratio combining: Select BF vector to maximize SNR: $\hat{\mathbf{w}} = \arg \max_{\mathbf{w}} \frac{|\mathbf{w}^* \mathbf{h}|^2 E_x}{\|\mathbf{w}\|^2 N_0}$

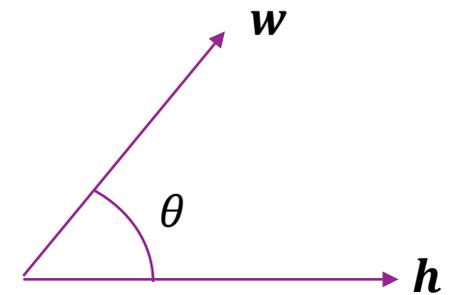
Theorem: The MRC weighting vector and maximum SNR is:

$$\hat{\mathbf{w}} = c \mathbf{h} \Rightarrow \gamma_{MRC} = \|\mathbf{h}\|^2 \frac{E_x}{N_0}$$

- Any constant $c \neq 0$ can be used. Constant does not matter
- Align BF vector with the channel.

Proof:

- From Cauchy-Schwartz: $|\mathbf{w}^* \mathbf{h}|^2 = \|\mathbf{w}\|^2 \|\mathbf{h}\|^2 \cos^2 \theta$
- Hence, $\gamma = \|\mathbf{h}\|^2 \frac{E_x}{N_0} \cos^2 \theta$
- Maximized with $\cos \theta = 1 \Rightarrow \theta = 0$



MRC Gain

- ❑ SNR with MRC: $\gamma_{MRC} = \|\mathbf{h}\|^2 \frac{E_x}{N_0}$
- ❑ SNR on channel i is: $\gamma_i = \frac{|h_i|^2 E_x}{N_0}$
- ❑ Average SNR is: $\gamma_{avg} = \frac{1}{M} \sum_{i=1}^M \gamma_i = \frac{1}{M} \sum_{i=1}^M |h_i|^2 \frac{E_x}{N_0} = \frac{1}{M} \|\mathbf{h}\|^2 \frac{E_x}{N_0}$
- ❑ MRC increases SNR by a factor of M relative to average per channel SNR
- ❑ Beamforming gain = $\frac{\gamma_{MRC}}{\gamma_{avg}} = M$
- ❑ Example: Suppose average SNR per antenna is 10 dB.
 - With $M = 16$ antennas and MRC, $\text{SNR} = 10 + 10 \log_{10}(16) = 10 + 4(3) = 22$ dB
 - Gain increases significantly!

RX Beamforming

□ Recall model for a single path channel:

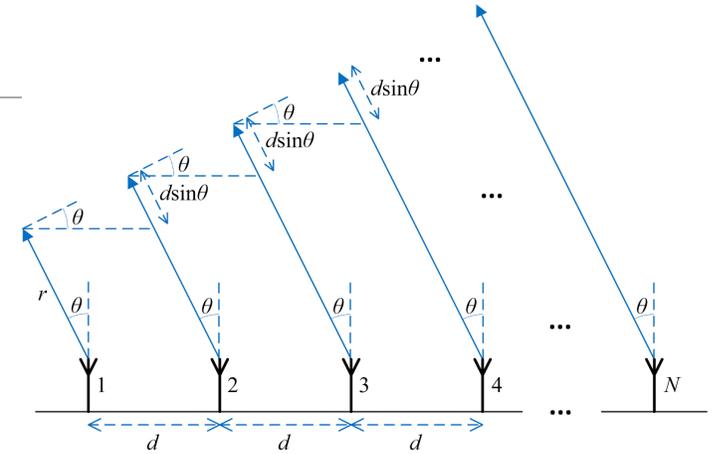
$$\mathbf{r} = g_0 \mathbf{u}(\Omega)x + \mathbf{n}$$

- $\mathbf{u}(\Omega)$ = spatial signature on that angle, Ω = angle of arrival
- g_0 = gain at reference position in array
- x = transmitted symbol

□ RX beamforming is just linear combining across antennas

$$z = \mathbf{w}^* \mathbf{r}$$

- \mathbf{w} is called the **beamforming vector**
- By convention, we assume $\|\mathbf{w}\| = 1$
- Geometric interpretation to be given shortly



MRC Beamforming

□ Single path channel: $\mathbf{r} = g_0 \mathbf{u}(\Omega)x + \mathbf{n}$

□ RX beamforming: $z = \mathbf{w}^* \mathbf{r}$

□ SNR per antenna (before beamforming):

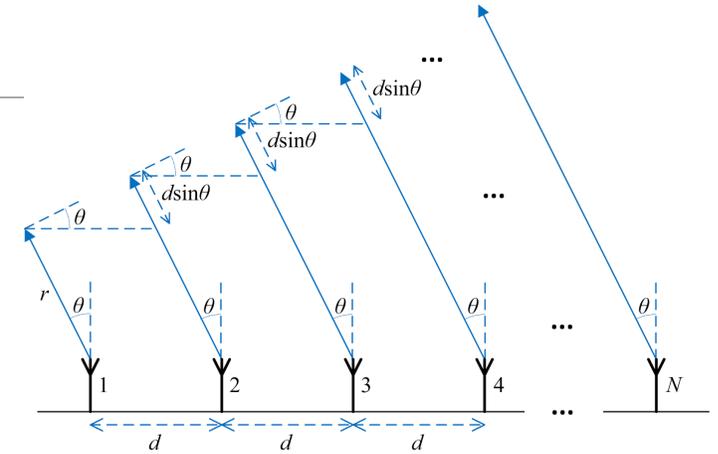
- $\gamma_0 = \frac{E_x |g_0|^2}{N_0} |u_m(\Omega)|^2 = \frac{E_x |g_0|^2}{N_0}$
- Assume $u_m(\Omega)$ includes only phase shifts

□ SNR after BF: $\gamma = \frac{|\mathbf{w}^* \mathbf{u}(\Omega)|^2}{\|\mathbf{w}\|^2} \gamma_0$

□ MRC beamforming: $\hat{\mathbf{w}} = c \mathbf{u}(\Omega)$ and $\gamma = \|\mathbf{u}(\Omega)\|^2 \gamma_0 = M \gamma_0$

□ Conclusions:

- Optimal (MRC) beamforming vector is aligned to the spatial signature
- Optimal SNR gain = M
- Linear gain with number of antennas



Example Problem

□ Consider a system

- TX power = 23 dBm with antenna directivity = 10 dBi
- Free space path loss $d = 1000$ m
- Sample rate = 400 Msym/s
- Noise energy = -170 dBm/Hz (including NF)
- RX antenna directivity = 5 dBi and 8 elements

SNR per ant: 0.59

SNR with MRC: 9.62

□ Find SNR per antenna and SNR with MRC

□ Solution: We get a 9 dB gain!

```
% SNR per antenna
plomni = fspl(dist, lambda);
EsNOAnt = ptx - plomni - 10*log10(bw) - Enoise + dirtx + dirrx;

% SNR with MRC
EsNOMRC = EsNO + 10*log10(nantrx);
```

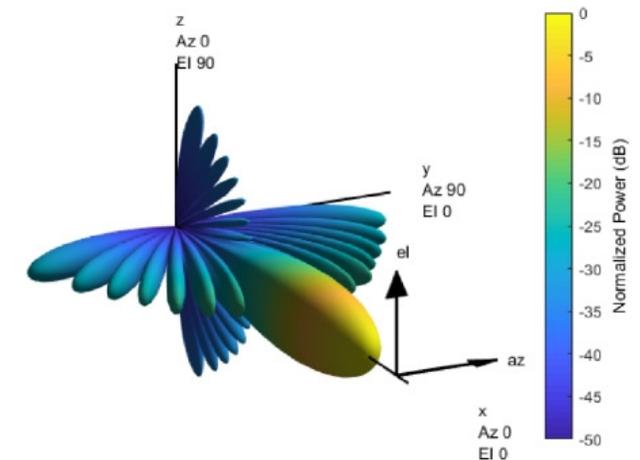
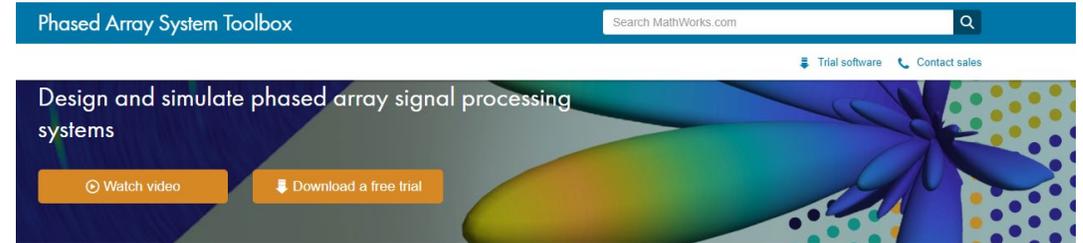


MATLAB Phased Array Toolbox

☐ Powerful toolbox

☐ Routines for:

- Defining and visualizing arrays
- Computing beam patterns
- Beamforming
- MIMO
- Radar
- ...



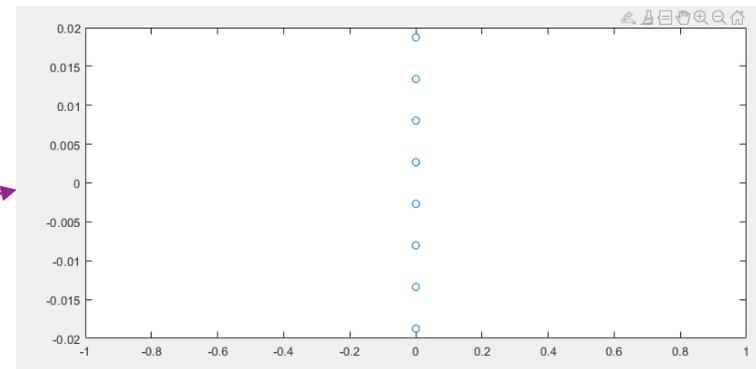
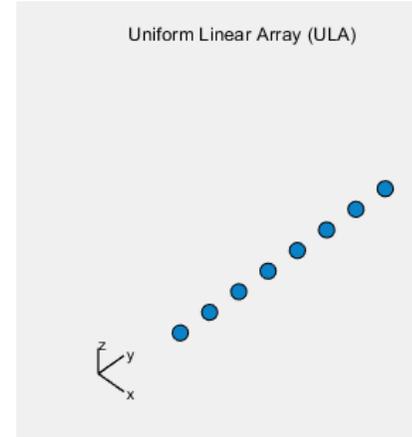
Example: Defining a ULA

- ❑ Define and view the array
- ❑ Can display array:
 - Using viewArray command
 - Or, manually

```
%% Uniform Linear Array
% We first define a simple uniform linear array
fc = 28e9;           % frequency
lambda = physconst('LightSpeed')/fc;
dsep = 0.5*lambda;  % element spacing
nant = 8;           % Number of elements
arr = phased.ULA(nant,dsep);

% View the array
viewArray(ula,'Title','Uniform Linear Array (ULA)')
```

```
elemPos = arr.getElementPosition();
clf('reset');
plot(elemPos(1,:), elemPos(2,:), 'o');
```



Computing the Spatial Signature

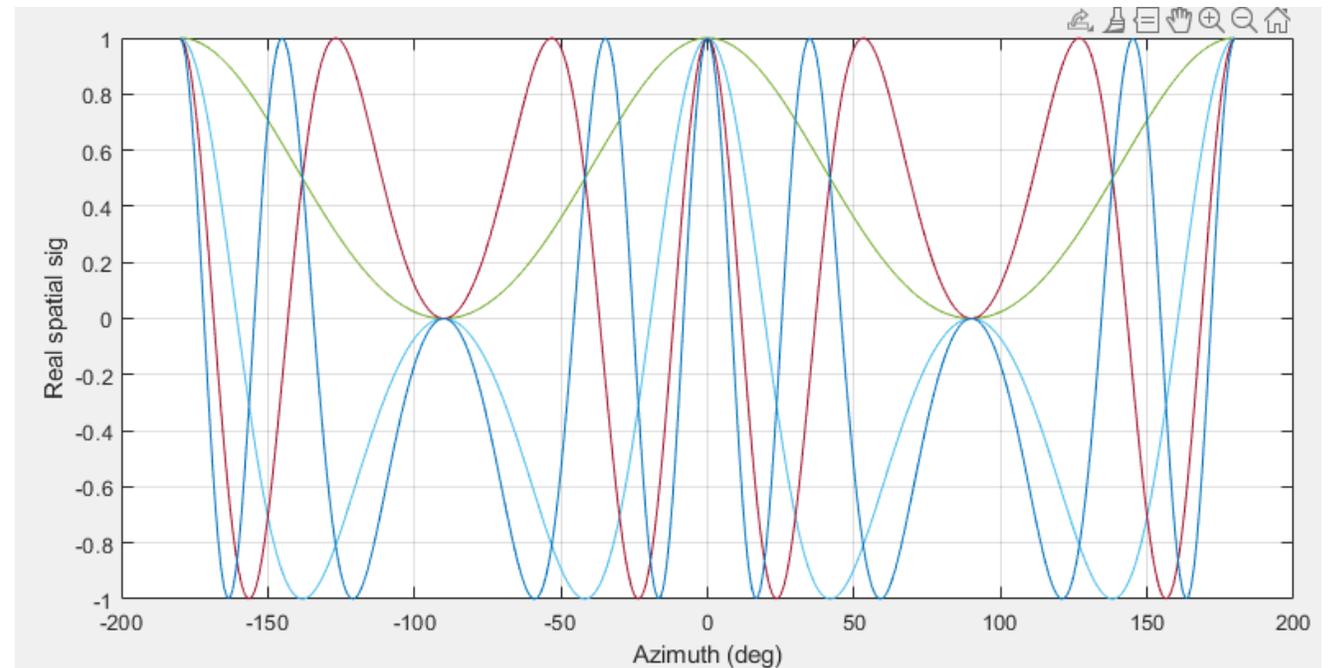
- Compute the spatial signature with the SteeringVector object

```
% Create a steering vector object
sv = phased.SteeringVector('SensorArray',arr);

% Angles to compute the SVs
npts = 361;
az = linspace(-180,180,npts);
el = zeros(1,npts);
ang = [az; el];

% Matrix of steering vectors
% This is an nant x npts matrix in this case
u = sv(fc, ang);

% Plot of the real components
plot(az, real(u)');
grid on;
xlabel('Azimuth (deg)')
ylabel('Real spatial sig');
```

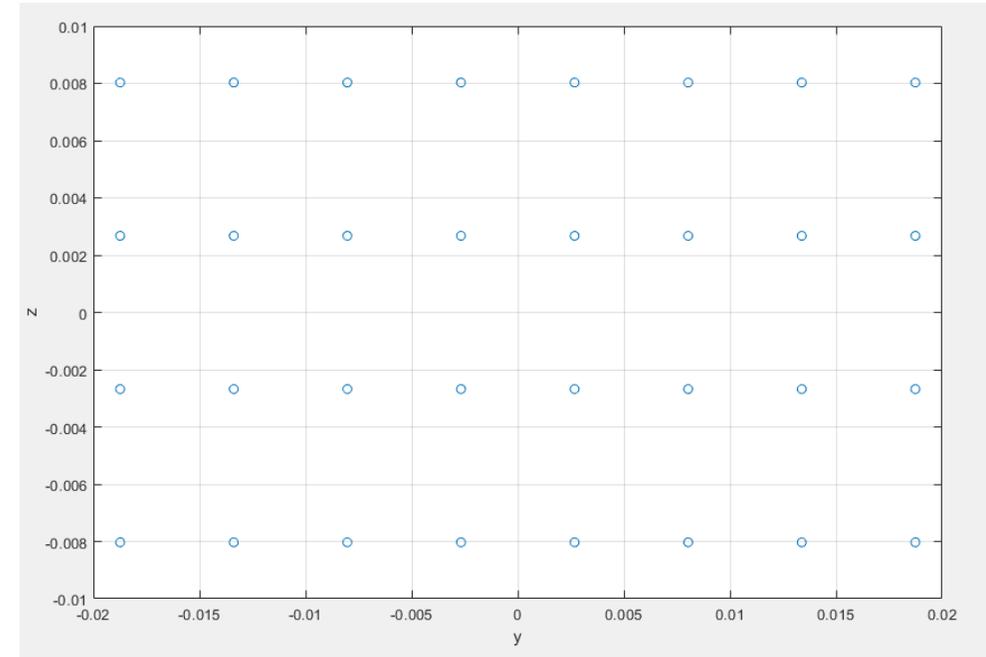


Example: Defining a URA

- ❑ Define and view the array
- ❑ Use the phased.URA class
- ❑ Can compute steering vector similarly

```
% Construct the array
nant = [4,8];
dsep = 0.5*lambda;
arr = phased.URA(nant,dsep,'ArrayNormal','x');

% Plot the array.
% You can also use, arr.viewArray()
elemPos = arr.getElementPosition();
clf('reset');
plot(elemPos(2,:), elemPos(3,:), 'o');
grid on;
xlabel('y');
ylabel('z');
```



A 4 x 8 URA with normal axis aligned on x

Multiple Antennas in Commercial Systems

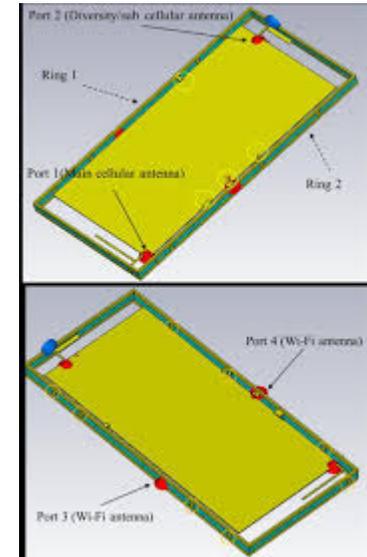
- ❑ Sub 6 GHz systems: Mostly 1 to 4 antennas on base stations or smart phones
- ❑ Form factor restricts larger number of antennas



WiFi Router
Linksys AC2200 with 4TX/RX



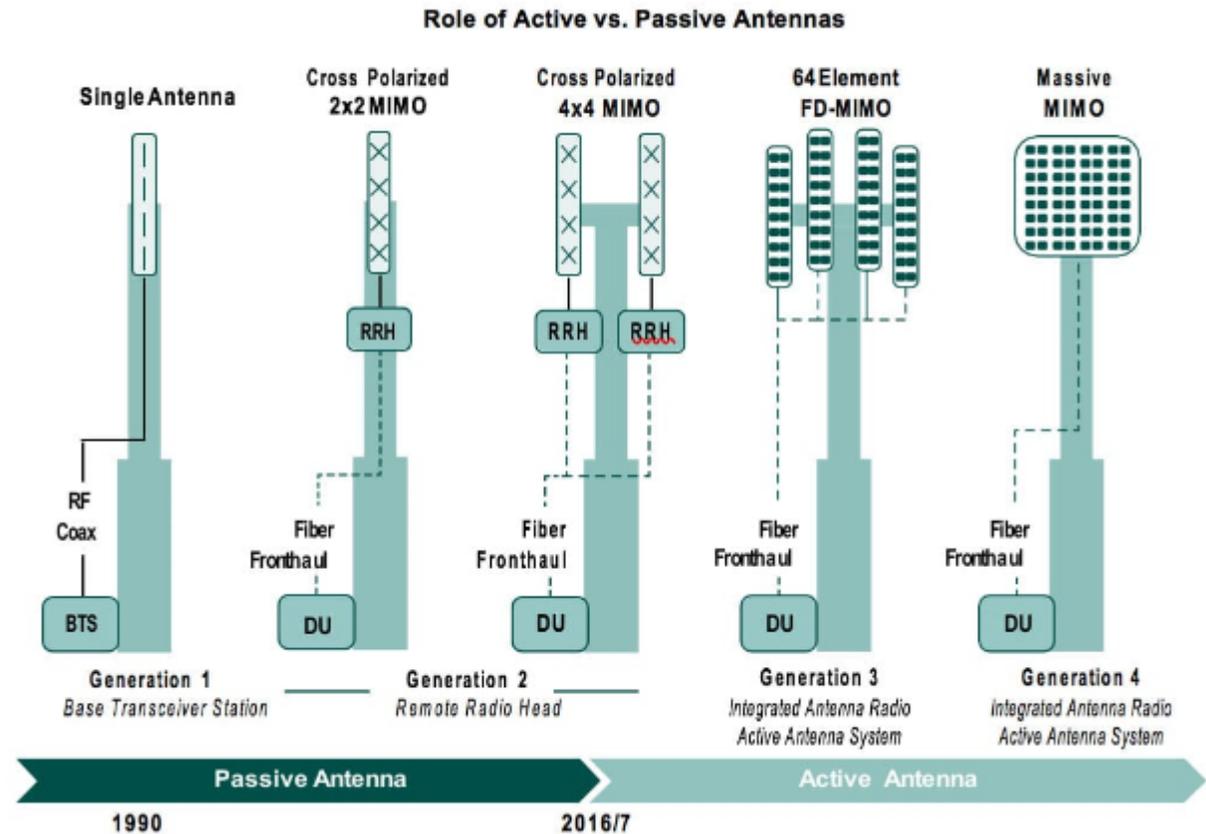
2x2 LTE base station antenna
Cros-polarization
16 dBi element gain, 90 deg sector
750x120x60mm



K. Zhao, S. Zhang, K. Ishimiya, Z. Ying and S. He, "Body-Insensitive Multimode MIMO Terminal Antenna of Double-Ring Structure," in *IEEE Transactions on Antennas and Propagation*, vol. 63, no. 5, pp. 1925-1936, May 2015.

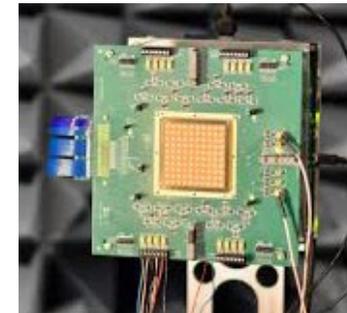
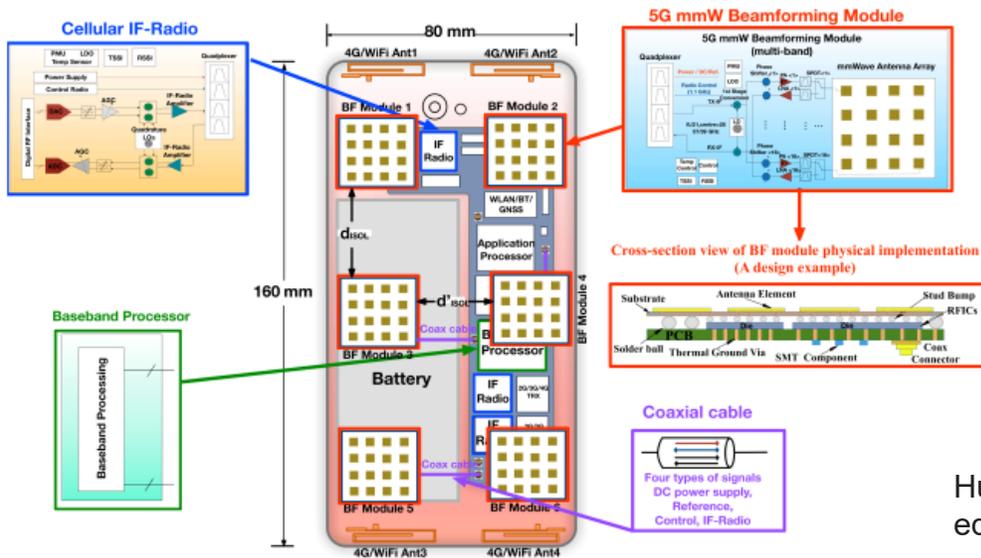
Massive MIMO

- ❑ Massive MIMO:
 - Many base station antennas
 - 64 to 128 in many systems today
- ❑ Significant capacity increase
 - Typically 8x by most estimates
- ❑ Use SDMA
 - Will discuss this later



Beamforming and MmWave

- ❑ To compensate for high isotropic path loss, mmWave systems need large number of antennas
- ❑ 5G handsets: Multiple arrays with 4 to 8 antennas each
- ❑ 5G base stations: 64 to 256 elements



IBM 28 GHz array
32 element dual polarized array
Sadhu et al, ISSCC 2017

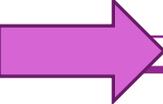
Huo, Yiming, et al. "Cellular and WiFi co-design for 5G user equipment." *2018 IEEE 5G World Forum (5GWF)*. IEEE, 2018.



In-Class Problem: Simple QPSK simulation

- Simulate QPSK transmission over a single path channel

Outline

- Antenna arrays and the Spatial Signature
- Receive Beamforming and SNR Gain
-  Array Factor
- Multiple Paths and Diversity
- Transmit Beamforming

Array Factor

□ Suppose RX aligns antenna for AoA $\Omega_0 = (\theta_0, \phi_0)$

□ But, signal arrives from AoA $\Omega = (\theta, \phi)$

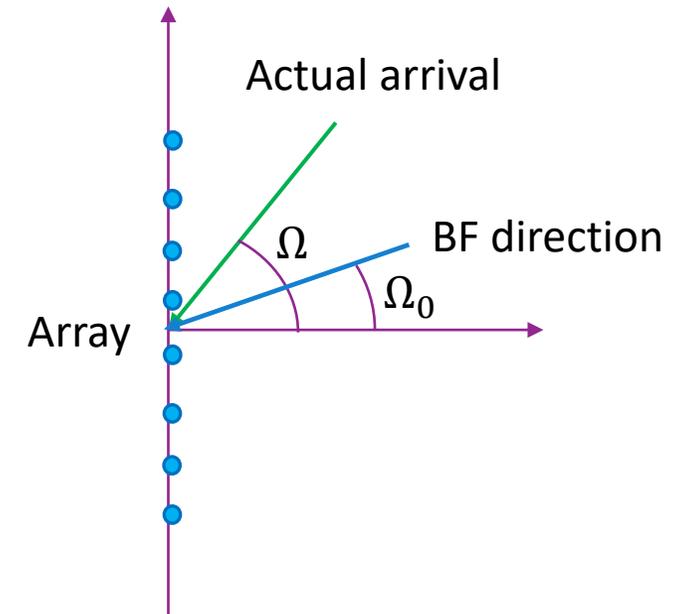
□ Define the (complex) **array factor**

$$AF(\Omega, \Omega_0) = \hat{\mathbf{w}}^*(\Omega_0)\mathbf{u}(\Omega) = \frac{1}{\sqrt{M}}\mathbf{u}^*(\Omega_0)\mathbf{u}(\Omega)$$

- Assume $\|\hat{\mathbf{w}}\| = 1$
- Indicates directional gain as a function of AoA θ
- Dependence on θ_0 often omitted

□ SNR gain = $|AF(\Omega, \Omega_0)|^2$

- Max value = M
- Usually measured in **dBi** (dB relative to isotropic)
- Also called the **array response**



Uniform Linear Array

□ Spatial signature (for azimuth angle ϕ):

- $\mathbf{u}(\phi) = [1, e^{j\beta}, \dots, e^{i(M-1)\beta}]^T$, $\beta = \frac{2\pi d \cos \phi}{\lambda}$
- Note change from $\sin \theta$ to $\cos \phi$. (Array aligned on y-axis)

□ Optimal BF vector for AoA ϕ_0

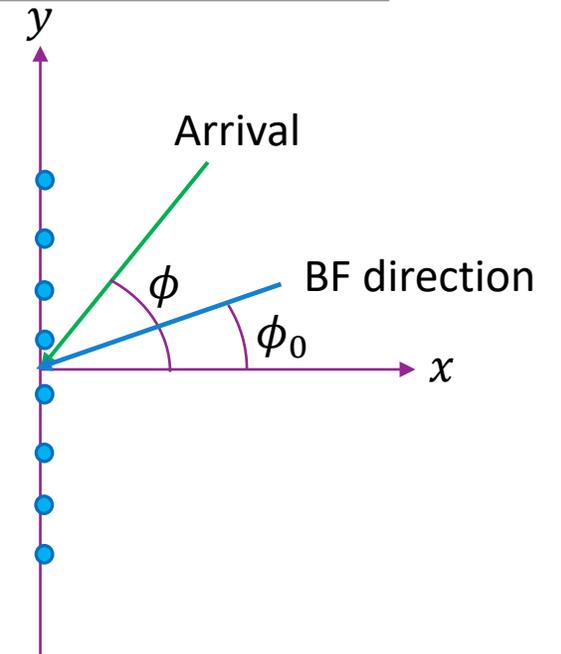
- $\hat{\mathbf{w}}(\phi_0) = \frac{1}{\sqrt{M}} \mathbf{u}(\phi_0)$ (Note normalization)

□ Array factor:

$$AF(\phi, \phi_0) = \hat{\mathbf{w}}(\phi_0)^* \mathbf{u}(\phi) = \frac{e^{j(M-1)\gamma/2} \sin(M\gamma/2)}{\sqrt{M} \sin(\gamma/2)},$$

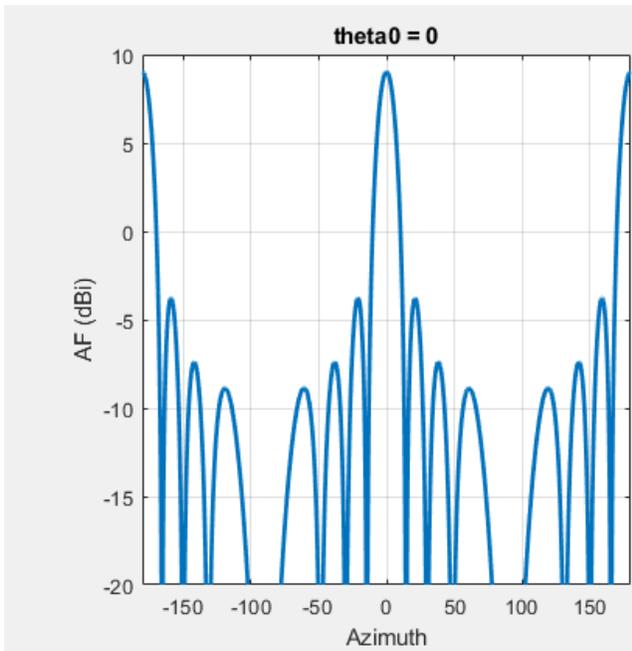
- $\gamma = \frac{2\pi d}{\lambda} (\cos \phi - \cos \phi_0)$,

□ Antenna gain: $|AF|^2 = \frac{\sin^2(M\gamma/2)}{M \sin^2(\gamma/2)}$

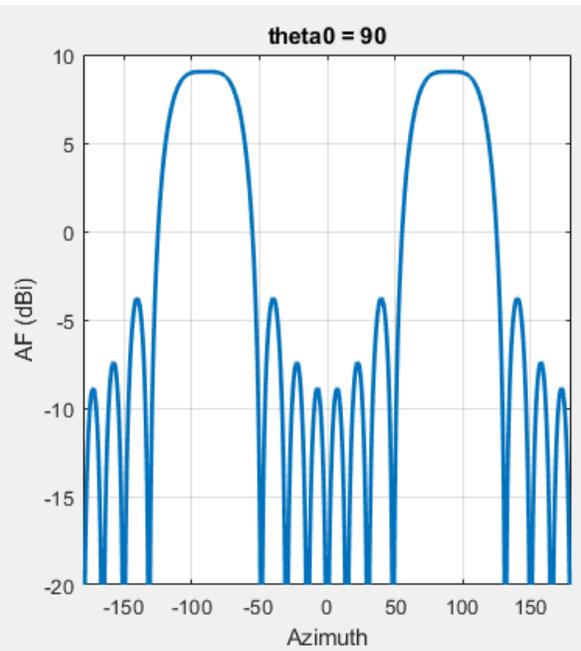


Antenna Gain for ULA

Broadside: $\theta_0 = 0$



Endfire: $\theta_0 = 90$

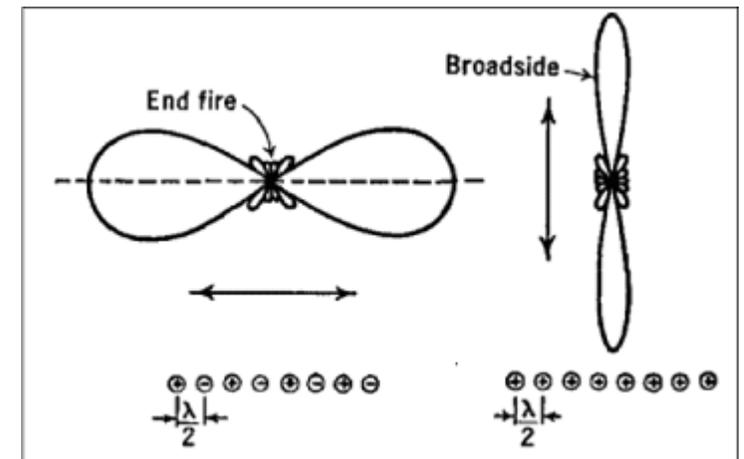


$$d = \lambda/2, \quad M = 8$$

Maximum gain of

Note:

- Endfire vs. broadside
- Beamwidth $\propto 1/M$



Plotting the Array Factor

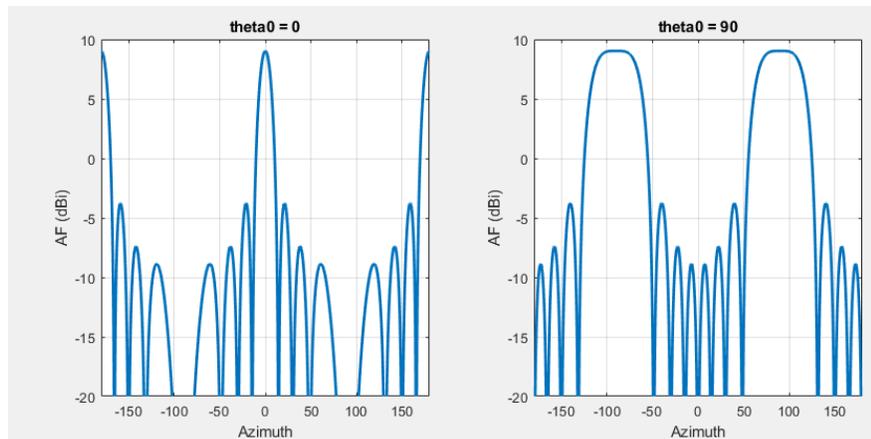
❑ Create a SteeringVector object

❑ Get steering vectors

❑ Compute inner products

```
% Create a steering vector object  
sv = phased.SteeringVector('SensorArray',arr);
```

```
% Reference angles to plot the AF  
azPlot = [0, 90];  
nplot = length(azPlot);
```

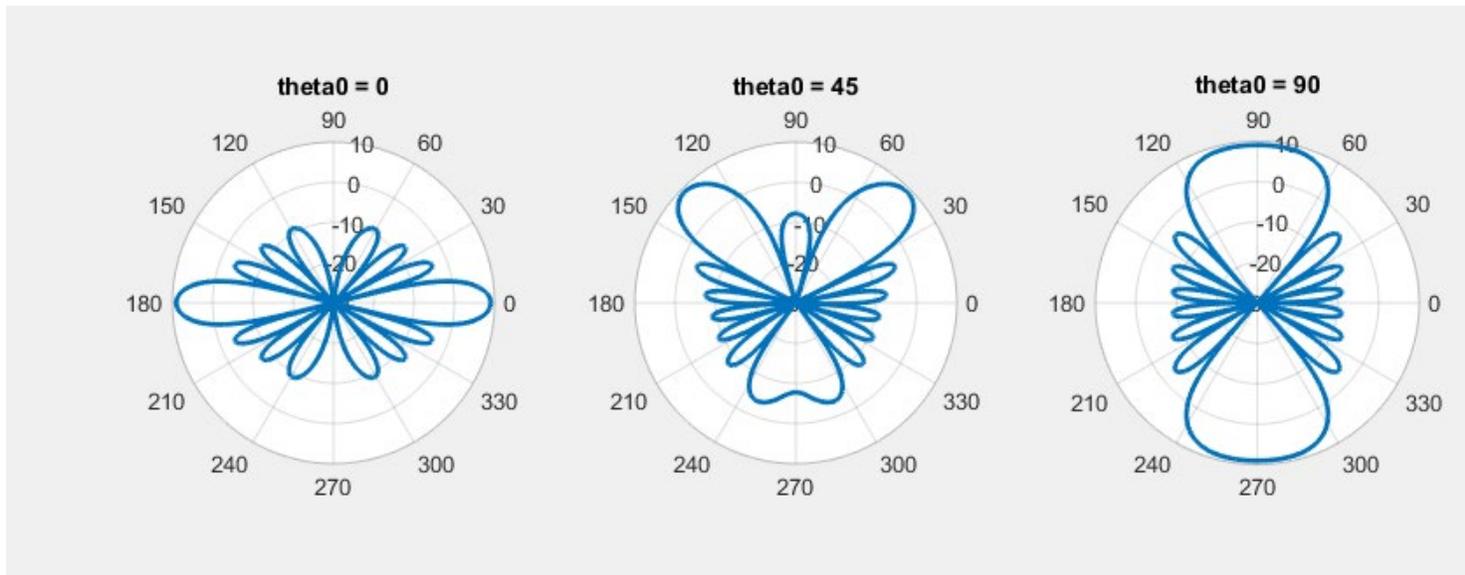


```
for iplot = 1:nplot  
    % Get the SV for the beam direction.  
    % Note: You must call release method of the sv  
    % before each call since it expects the same size  
    % of the input  
    ang0 = [azPlot(iplot); 0];  
    sv.release();  
    u0 = sv(fc, ang0);  
  
    % Normalize the direction  
    u0 = u0 / norm(u0);  
  
    % Get the SV for the AoAs. Take el=0  
    npts = 1000;  
    az = linspace(-180,180,npts);  
    el = zeros(1,npts);  
    ang = [az; el];  
    sv.release();  
    u = sv(fc, ang);  
  
    % Compute the AF and plot it  
    AF = 10*log10( abs(sum(conj(u0).*u, 1)).^2 );  
  
    % Plot it  
    subplot(1,nplot,iplot);  
    plot(ang(1,:), AF, 'LineWidth', 2);  
  
end
```

Polar Plot

- Useful to visualize in polar plot
- Note key features:
 - Direction of maximum gain
 - Sidelobes
 - Pattern repeated on reverse side

```
% Polar plot
AFmin = -30;
subplot(1,nplot,iplot);
polarplot(deg2rad(az), max(AF, AFmin), 'LineWidth', 2);
rlim([AFmin, 10]);
grid on;
```



Key Statistics

	Broadside ($\theta_0 = \pi/2$)	End-fire ($\theta_0 = 0$)
Full null beamwidth (zero to zero)	FNBW $2 \left[\frac{\pi}{2} - \cos^{-1} \left(\frac{\lambda}{N\Delta} \right) \right]$ (30°)	$2 \cos^{-1} \left(1 - \frac{\lambda}{N\Delta} \right)$ (83°)
Half power beamwidth (-3dB to -3dB)	HPBW $2 \left[\frac{\pi}{2} - \cos^{-1} \left(\frac{1.39\lambda}{\pi N\Delta} \right) \right]$ (13°)	$2 \cos^{-1} \left(1 - \frac{1.39\lambda}{\pi N\Delta} \right)$ (54°)
First sidelobe level	FSL $\frac{1}{N \left \sin \left(\frac{3\pi}{2N} \right) \right }$ (-13 dB)	$\frac{1}{N \left \sin \left(\frac{3\pi}{2N} \right) \right }$ (-13 dB)
	D_0 $2N\Delta/\lambda$ (9 dB)	$4N\Delta/\lambda$ (12 dB)

□ From Jacobs University slides

□ Values in () for: $d = \lambda/2$, $M = 8$

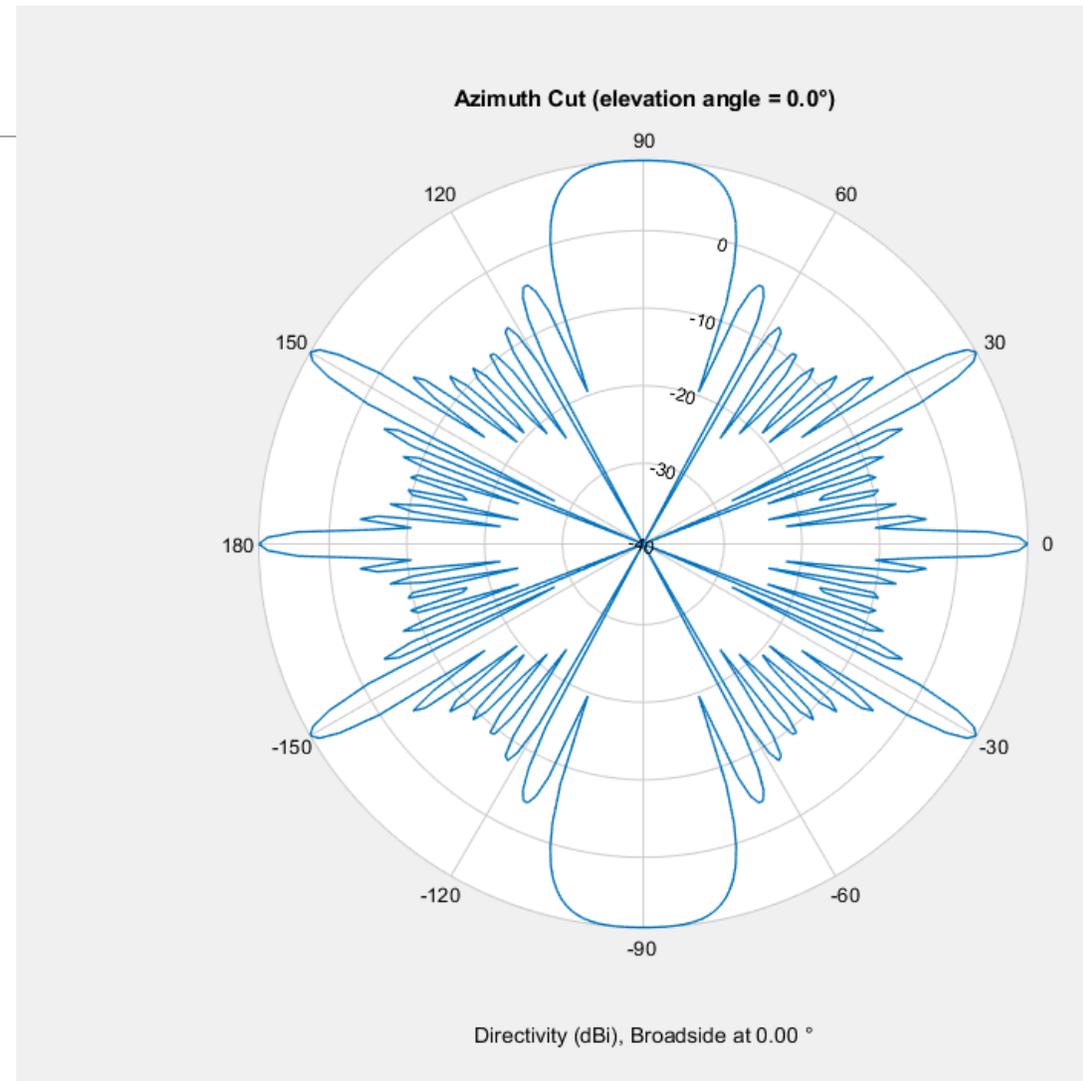


Grating Lobes

- When $d > \frac{\lambda}{2}$
- Obtain multiple peaks
- Does not direct gain in one direction

```
dsep = 2*lambda;      % element spacing
nant = 8;             % Number of elements
arr = phased.ULA(nant,dsep);
|
% Get the SV for the beam direction.
ang0 = [0; 0];
sv.release();
u0 = sv(fc, ang0);

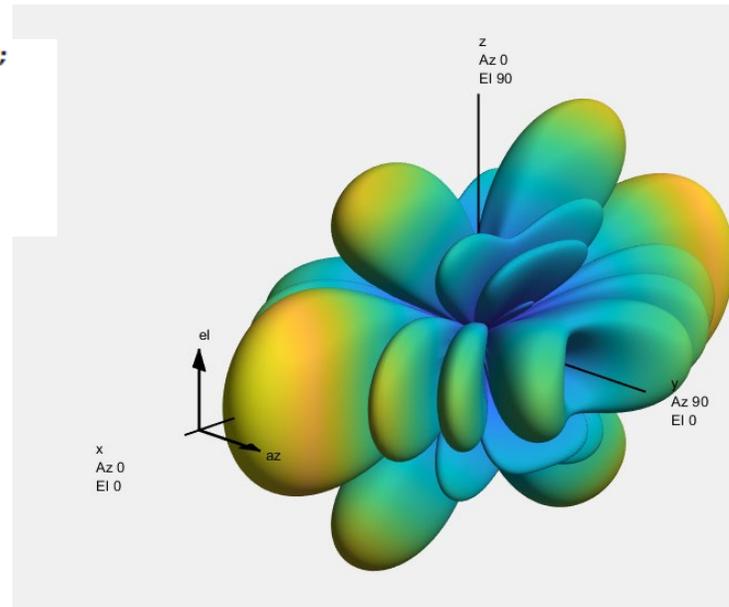
arr.patternAzimuth(fc, 'Weights', u0);
```



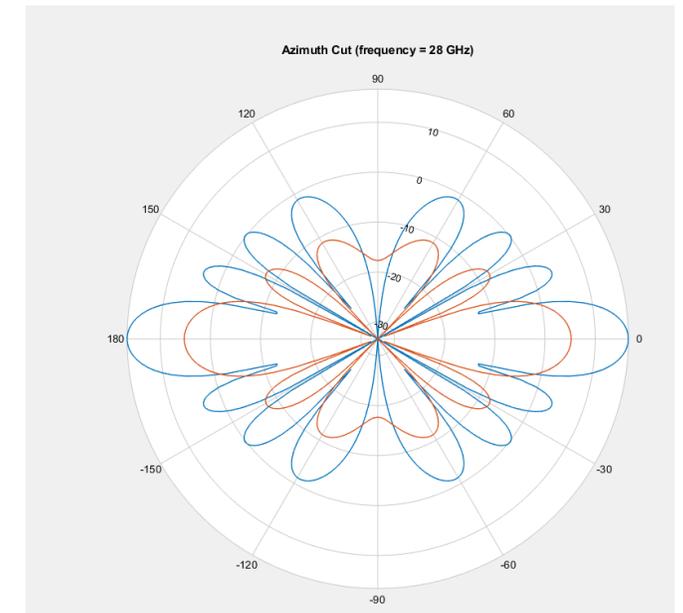
Plotting the Patterns

- ❑ MATLAB has excellent routines for 3D patterns
- ❑ Note that this plots directivity not array factor

```
sv = phased.SteeringVector('SensorArray',arr);  
ang0 = [0; 0];  
sv.release();  
u0 = sv(fc, ang0);  
u0 = u0 / norm(u0);
```



```
% We can plot the directivity in a 3D plot  
arr.pattern(fc, 'Weights', u0);
```



```
elPlot = [0 45];  
arr.patternAzimuth(fc, elPlot, 'Weights', u0);
```

Element Gain

- Above analysis assumes each element is omni-directional
- Each antenna element may also have gain.
- Assume all elements of an array are identical and have same orientation
- **Pattern multiplication theorem**: The frequency response of a single path channel is:

$$h(\omega) = g(\omega)A_E(\Omega)\mathbf{u}(\Omega)$$

Freq response @reference Element gain Spatial signature

- Resulting array factor (in linear scale): $AF(\Omega, \Omega_0) = AF_{\text{ISO}}(\Omega, \Omega_0)A_E(\Omega)$
 - $AF_{\text{ISO}}(\Omega, \Omega_0) = \frac{1}{\sqrt{M}}\mathbf{u}^*(\Omega_0)\mathbf{u}(\Omega)$ = array factor with isotropic elements

Example: URA with Patch Elements

Example 4x8 URA

Add patch element

- Element normal in +x direction
- Peak element gain ≈ 8 dBi
- Adds to the total array gain

Patch elements

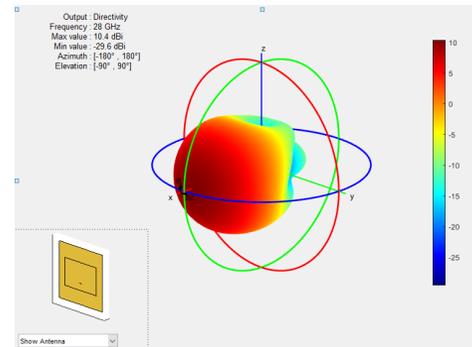
4 x 8 URA

Peak directivity ≈ 21 dB
Gain low in negative x direction

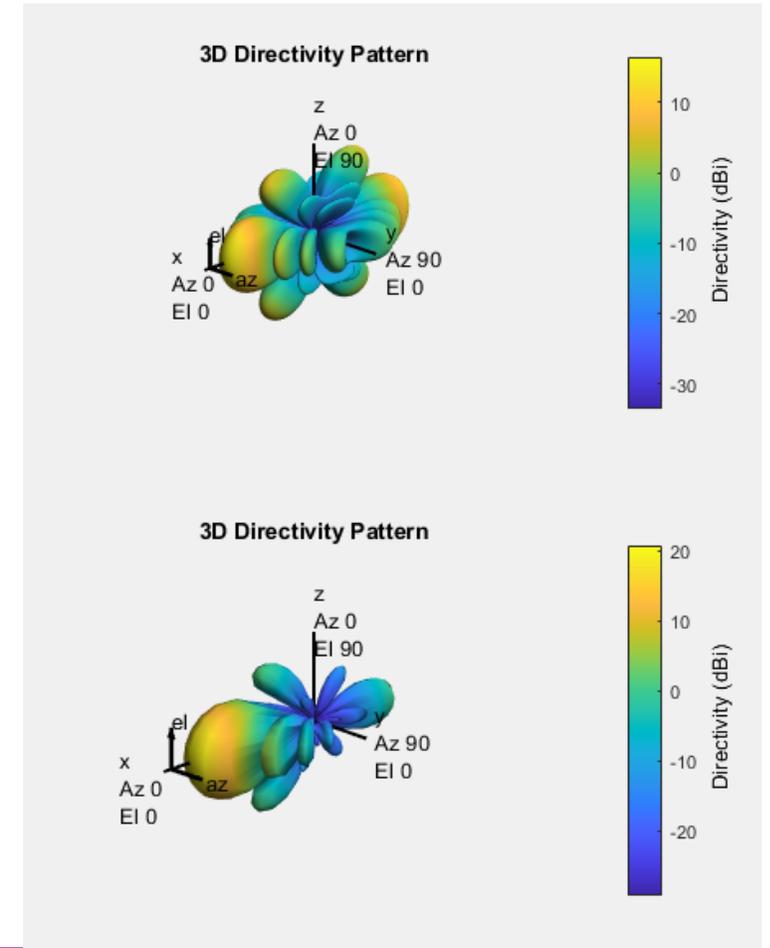
Isotropic elements

4 x 8 URA

Peak directivity ≈ 15 dB
Gain in both positive and negative x direction

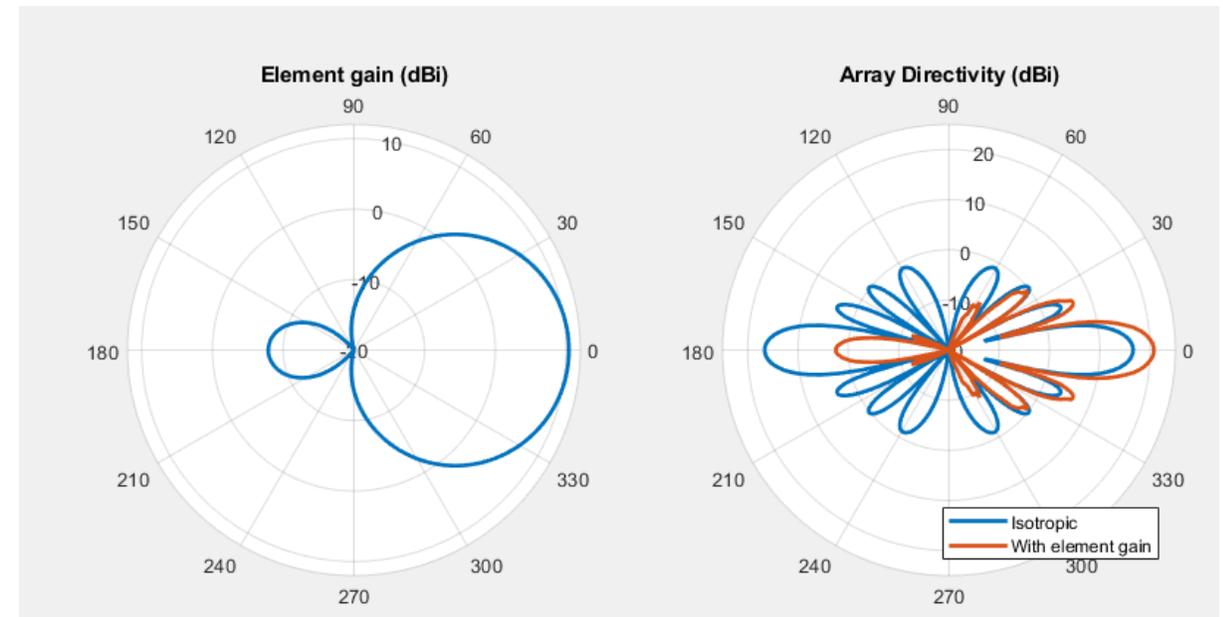


Element pattern



Example: URA with Patch Elements in 2D

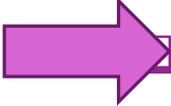
- ❑ Pattern multiplication in 2D
- ❑ Element gain increases directivity
- ❑ Note: MATLAB plots directivity
 - Does not plot array gain
 - Directivity is array gain normalized to one



In-Class Problem: Simulating BF Mismatch

- Continue simulation but with BF mismatch

Outline

- Antenna arrays and the Spatial Signature
- Receive Beamforming and SNR Gain
- Array Factor
-  Multiple paths and Diversity
- Transmit Beamforming

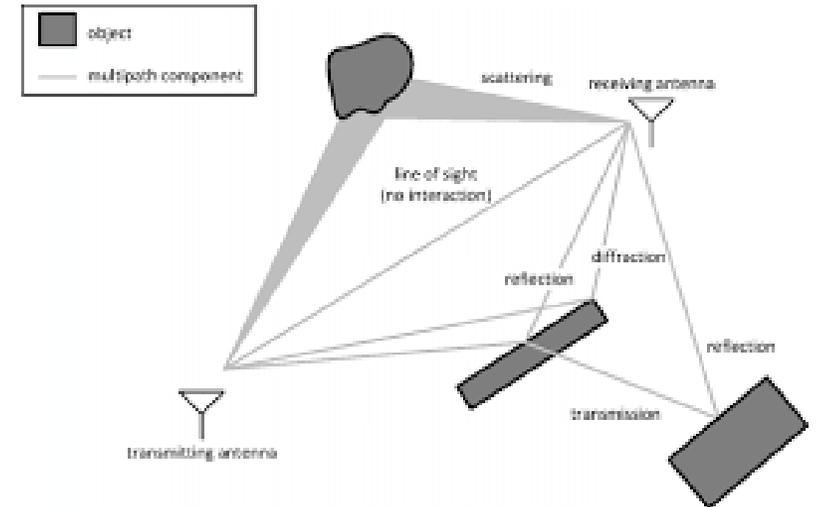


Multiple Paths

- Easy to extend channel response to multiple paths
- Each path adds a term with a spatial signature
- Time-domain model

$$\mathbf{r}(t) = \sum_{\ell=1}^L g_{\ell} e^{j\omega_{\ell} t} \mathbf{u}(\Omega_{\ell}) x(t - \tau_{\ell}) + \mathbf{n}(t)$$

Complex gain Doppler shift AoA Delay



Time-Varying Frequency Response

- Apply input $x(t) = e^{j\omega t}$
- RX vector is $\mathbf{r}(t) = \mathbf{h}(t, \omega)x(t)$
- Time-varying frequency response
- $\mathbf{h}(t, \omega) = \sum_{\ell=1}^L g_{\ell} e^{j\omega_{\ell} t - j\omega \tau_{\ell}} \mathbf{u}(\Omega_{\ell})$
- Vector channel response

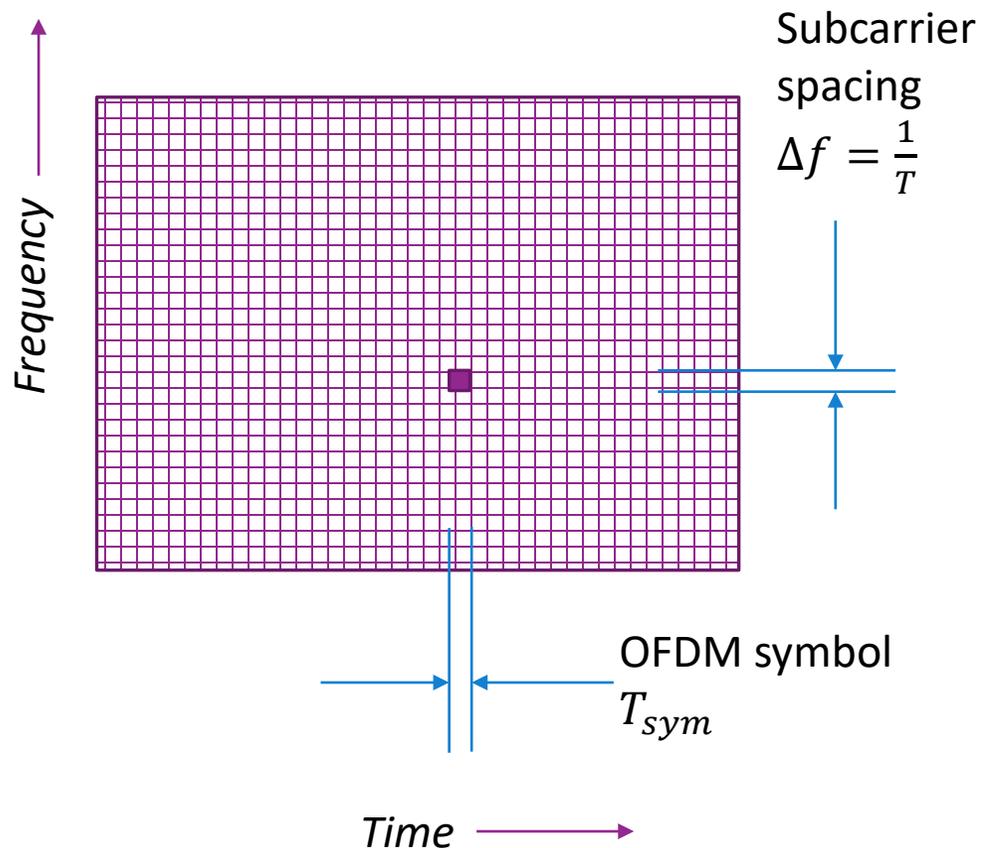
Time-Varying Frequency Response

- ❑ Multipath channel: $\mathbf{r}(t) = \sum_{\ell=1}^L g_{\ell} e^{j\omega_{\ell} t} \mathbf{u}(\Omega_{\ell}) x(t - \tau_{\ell})$
- ❑ Consider exponential scalar input: $x(t) = e^{j\omega t}$
- ❑ Vector output is: $\mathbf{r}(t) = \mathbf{h}(t, \omega)x(t)$
- ❑ Time-varying frequency response

$$\mathbf{h}(t, \omega) = \sum_{\ell=1}^L g_{\ell} e^{j(\omega_{\ell} t - \omega \tau_{\ell})} \mathbf{u}(\Omega_{\ell})$$

- ❑ May also write: $\mathbf{h}(t, f) = \mathbf{h}(t, 2\pi f)$

OFDM Time-Frequency Grid



- Recall OFDM from earlier lecture
- Divide channel into sub-carriers and OFDM symbols
 - **Resource element**: One time-frequency point
- Data is transmitted is an **array**: $X[n, k]$
 - k = OFDM symbol index, n = subcarrier index
 - One complex value per RE.
- Receive a vector:
$$\mathbf{Y}[n, k] = [Y_1[n, k], \dots, Y_M[n, k]]^T$$
 - One complex symbol per antenna per RE

OFDM Channel with Multiple RX Antennas

- OFDM channel acts as multiplication:
Under normal operation (delay spread is contained in CP):

$$Y[k, n] = H[k, n] X[k, n]$$

RX symbol vectors Vector channel TX symbols

- OFDM channel gains can be computed from the multi-path components

$$H[k, n] = \sum_{\ell=1}^L \sqrt{E_{\ell}} e^{-2\pi j (Tkf_{\ell} + Sn\tau_{\ell} + \phi_{\ell})} \mathbf{u}(\Omega_{\ell})$$

- T = OFDM symbol time, S = sub-carrier spacing
- For each path: f_{ℓ} = Doppler shift, τ_{ℓ} = Delay, ϕ_{ℓ} = phase of path, E_{ℓ} = path received energy

Time Scales

- Consider vector channel response

$$\mathbf{h}(t, \omega) = \sum_{\ell=1}^L g_{\ell} e^{j\omega_{\ell} t - j\omega \tau_{\ell}} \mathbf{u}(\Omega_{\ell})$$

- Large scale parameters: Change slowly

- Gain g_{ℓ} and angles Ω_{ℓ}
- Depend on geometry and large obstacles.

- Small scale parameters: Change rapidly

- $\omega \tau_{\ell}$: Changes over frequency on order of inverse delay spread
- $\omega_{\ell} t$: Changes over time on order of Doppler spread

RX Correlation

□ How correlated are two different antennas?

- Related to diversity gain

□ Covariance matrix

$$\mathbf{Q} = \text{cov}[\mathbf{h}(t, \omega)] = E(\mathbf{h}(t, \omega) - \boldsymbol{\mu})(\mathbf{h}(t, \omega) - \boldsymbol{\mu})^*$$

□ Typically fix AoA and path gains, average over ω and t

□ Averaging over time and frequency: $E\mathbf{h}(t, \omega) = 0$ and

$$\mathbf{Q} = \sum_{\ell=1}^L |g_{\ell}|^2 \mathbf{u}(\Omega_{\ell}) \mathbf{u}(\Omega_{\ell})^*$$

- Proof on board

Correlation with Random AoAs

□ Suppose:

- ULA with M elements
- L large. Total power gain G
- AoAs spread θ had pdf $p(\theta)$

□ Then:

$$Q_{km} = G \int_0^{2\pi} p(\theta) e^{ikd(k-m) \cos \theta} d\theta$$



Correlation with Uniform AoAs

□ If θ uniform $[0, 2\pi]$

□ Then:

$$Q_{jm} = \frac{G}{2\pi} \int_0^{2\pi} e^{ikd(j-m) \cos \theta} d\theta = J_0 \left(\frac{2\pi d_{jm}}{\lambda} \right)$$

- $d_{jm} = d(j - m)$ distance between antennas
- $J_0(x)$ = Bessel function

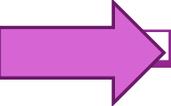
□ Become uncorrelated when $d_{jm} \gg \lambda$

□ Need more spacing for smaller range of angles

Diversity Gain

- ❑ Peak gain does not depend on antenna size
- ❑ High diversity gain requires wide separation
- ❑ Example:
 - $f_c = 3$ GHz
 - $\lambda = 10$ cm
 - Antenna separation $10\lambda = 1$ m
 - Possible in a cellular tower.
 - Not possible in a handset

Outline

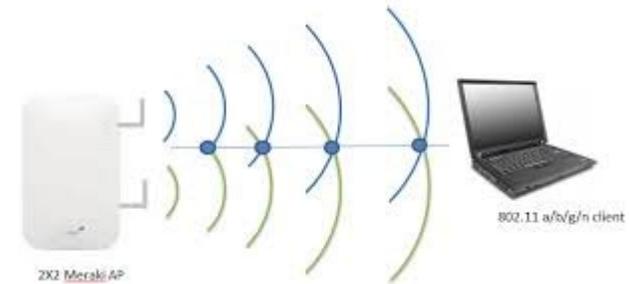
- Antenna arrays and the Spatial Signature
- Receive Beamforming and SNR Gain
- Array Factor
- Multiple paths and Diversity
-  Transmit Beamforming

Multiple TX antennas

□ MISO channel

- Multiple input single output
- M TX antennas, 1 RX antennas
- Transmit vector: $\mathbf{x}(t) = (x_1(t), \dots, x_M(t))^T$
- Scalar RX: $r(t)$

□ Most of the theory is identical to the SIMO channel

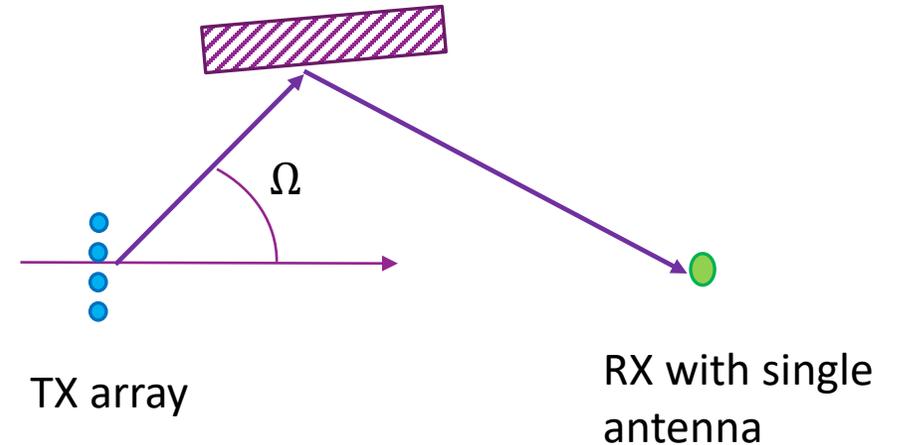


Single Path Channel

- First consider single path channel
- Similar to SIMO case, RX signal is:

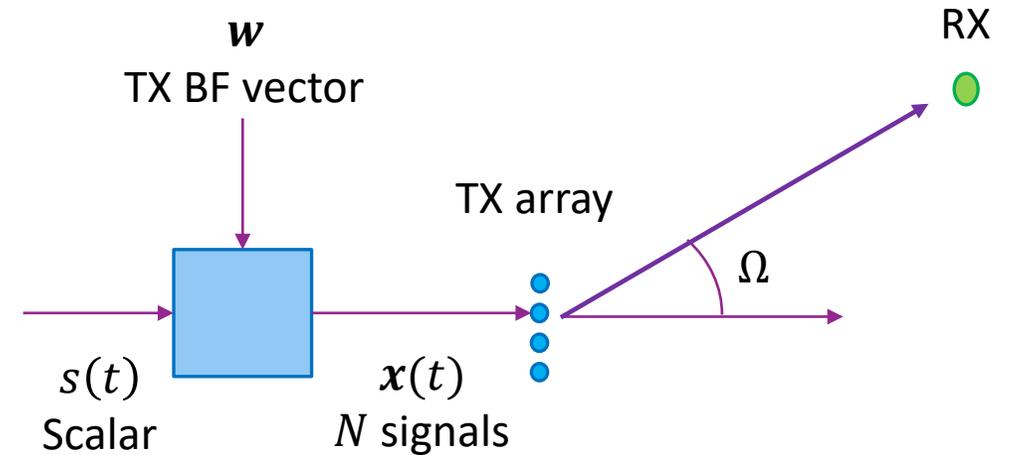
$$r(t) = g_0 \mathbf{u}^*(\Omega) \mathbf{x}(t - \tau)$$

- g_0 path gain
 - Ω = angle of departure
 - τ = path delay
 - $\mathbf{u}^*(\Omega)$ spatial signature
- TX and RX spatial signatures are identical
 - Except you apply the conjugate transpose



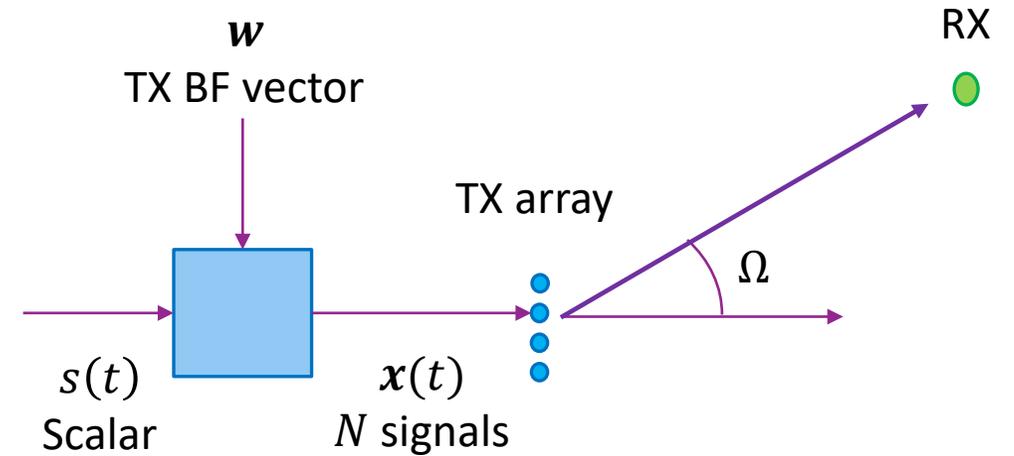
TX Beamforming

- ❑ RX signal is: $r(t) = g_0 \mathbf{u}^*(\Omega) \mathbf{x}(t - \tau) + n(t)$
- ❑ TX beamforming
 - Input scalar information signal $s(t)$
 - Create vector signal to antennas: $\mathbf{x}(t) = \mathbf{w} s(t)$
 - \mathbf{w} is called the TX **beamforming vector**
- ❑ Also called **pre-coding**



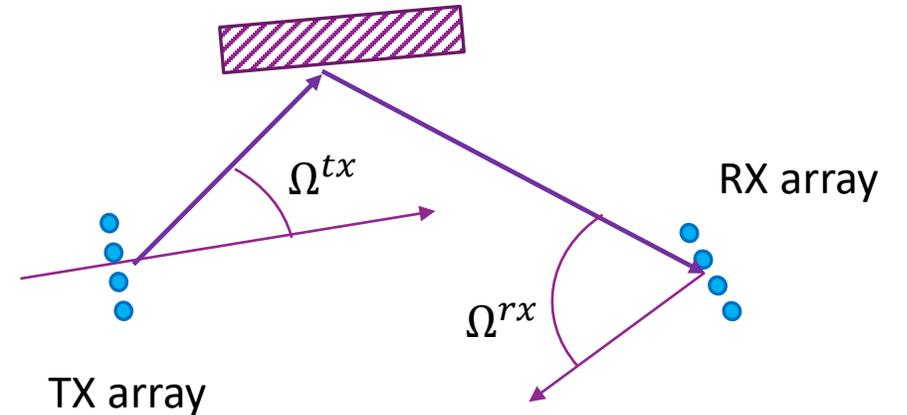
MRC TX Beamforming

- ❑ RX signal is: $r(t) = g_0 \mathbf{u}^*(\Omega) \mathbf{x}(t - \tau) + n(t)$
- ❑ Analysis is identical to SIMO case
- ❑ MRC TX BF vector: $\hat{\mathbf{w}} = \frac{1}{\sqrt{N}} \mathbf{u}(\Omega)$
 - Align with AoD
- ❑ SNR gain = N
- ❑ Define and compute Array Factor similarly
- ❑ Also define multi-path channel



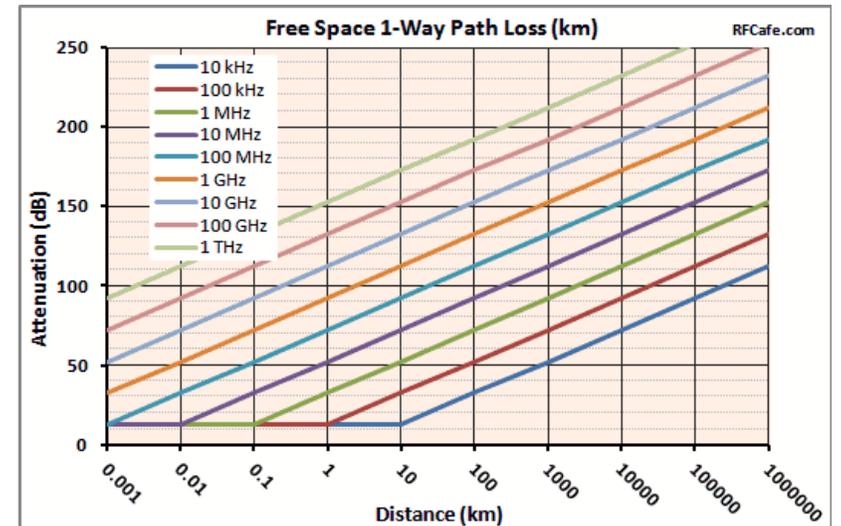
Beamforming and Channel Estimation

- ❑ Key issue for beamforming: Channel estimation
- ❑ TX and RX beamforming require that channel is known
- ❑ We will discuss many of these concepts later
 - Reference signals
 - Channel feedback
 - Channel tracking
 - Beam management
 - Spatial equalization



Friis' Law and MmWave

- Recall Friis' Law: $\frac{P_r}{P_t} = D_1 D_2 \left(\frac{\lambda}{4\pi R} \right)^2$
- Isotropic path loss decreases with λ^2
- Millimeter Wave systems: Increases f_c^2
 - Decreases $\lambda^2 \Rightarrow$ Increase path loss
 - Compensate isotropic path loss with directivity, D_i
- Fix aperture A_1 on TX side, A_2 on receiver side
 - Can fit $N_i = \frac{cA_i}{\lambda^2}$ antennas on each side
 - Leads to directivity: $D_i \propto N_i \propto \frac{A_i}{\lambda^2}$
- Can compensate isotropic path loss with directivity



Friis' Law and MmWave

Condition	Directivity scaling	Path loss scaling
No beamforming	D_i constant	$PL \propto f_c^2$
Beamforming on one side (TX or RX)	$D_1 \propto f_c^2$, D_2 constant	PL constant
Beamforming on both sides (TX and RX)	$D_1, D_2 \propto f_c^2$	$PL \propto f_c^{-2}$

□ Friis' Law: $\frac{P_r}{P_t} = D_1 D_2 \left(\frac{\lambda}{4\pi R} \right)^2$

□ Conclusions: With a fixed aperture and beamforming

- Isotropic path loss can be overcome

□ But systems need very directive beams

- Raises many other issues. E.g. Channel tracking, processing, ...